Full waveform modeling of the earth's mantle at the global scale: from normal modes to SEM

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Acknowledging contributions by: X.D. Li, <u>V. Lekic</u>, <u>S. French</u>, H. Yuan Long period seismograms by normal mode summation

1) Spherically symmetric Earth (1D)

$$u(\mathbf{x},t) = \operatorname{Re} \left\{ \sum_{k} A_{k}^{0}(\Delta) e^{i\omega_{k}t} \right\}$$
Eigenfrequency
distance
Source excitation

2) 3D Earth - First order perturbation theory Step 1: high frequency approximation

$$u(\mathbf{x},t) = \operatorname{Re}\left\{\sum_{\gamma} A_{k}^{0}(\Delta)e^{i(\omega_{k}+\delta\hat{\omega}_{k})t}\right\}$$
$$\delta\hat{\omega}_{k} = \frac{1}{2\pi}\int_{\gamma} \delta\omega(s)ds \qquad \text{Eigenfrequency shift}$$

3) "Path average approximation (PAVA)"

$$u(\mathbf{x},t) = \operatorname{Re}\left\{\sum_{k} A_{k}^{0} (\Delta + \delta \Delta) e^{i(\omega_{k} + \delta \hat{\omega}_{k})t}\right\}$$



Great circle average

-> Introduced by Woodhouse and Dziewonski (1984)

-> Equivalent to surface wave PAVA approximation (Mochizuki, 1986; Romanowicz, 1987)

Time domain waveform inversion in global seismology

Woodhouse and Dziewonski (1984)



- Normal mode theory
- Path AVerage Approximation (PAVA)->
 1D sensitivity kernels
- Later, complement with body wave travel times (ray theory) to access lower mantle structure



Full Waveform Tomography of the whole mantle



- To include body waveforms with the "correct" sensitivity Concentrated along the raypath, one needs to include across branch coupling (Li and Romanowicz, 1995; Marquering et al., 1996)



l: angular order, horizontal nodesn: overtone number, vertical nodes

4) Non-linear asymptotic coupling theory (NACT)-> 2D Kernels in the vertical plane (Li and Romanowicz, 1995)



Full Waveform Tomography of the whole mantle



- NACT: Surface waves, overtones (T>80s), body waves (T>32 s)

-Misfit function: Windowing to allow weighing of wavepackets, in order to equalize amplitudes.

-Several generations of whole mantle shear velocity models, -Including radial anisotropy, attenuation





Isotropic Vs Depth = 2800 km





 $\delta v_{S}^{\prime}/v_{S}^{\prime}[\%]$



Replace mode synthetics by numerical synthetics computed using the Spectral Element Method (SEM)

UC Berkeley Global Seismology Group

Challenges for SEM based global waveform tomography

Computation time:

- One event periods > 60s: 4 hours on 32 cores
- Need several hundred events, many iterations

The earth's crust:

- Strongly heterogeneous
- Thin low velocity layers → slows down the computation
- Crustal structure is not perfectly known at the global scale
- Strong non-linearity \rightarrow cycle slips

Our strategy

- Take "modest steps" and in the process learn something about the earth
- Start at long periods (T> 60s)
- Progressively add waveforms as observed and predicted phases line up
- Compute forward wavefield precisely using C-SEM
- Compute inverse Hessian kernels approximately (NACT)
- Use "homogenized", smooth crustal model appropriate for the period range considered

I-HYBRID INVERSION APPROACH

At each iteration:

1-Forward modeling step

Use coupled spectral element method of Capdeville et al. (2003) to accurately forward model wave propagation through the 3D Earth



 Γ 1= Normal modes in 1D Γ 2 = Spectral element method

2-Inverse step

Use approximate Hessian calculated in NACT. Much faster than adjoint!



Li and Romanowicz, 1995

II-NACT kernels

- Based on asymptotic mode coupling theory
- updated with each update of the model (PAVA term includes multiple forward scattering)
- We use the Hessian rather than a gradient method
- Can account for attenuation effects accurately

Adjoint kernels

- Computed numerically
 - single scattering approximation

 Conjugate Gradient method

Attenuation approximated

III-Smooth homogeneized crustal model Equivalent smooth anisotropic layer (Backus, 1962)

Two generations of models:

- SEMum - 60 km constant Moho (Lekic and Romanowicz, 2011)

- SEMum2- variable >30 km

In both cases:
Start with Clipped, filtered Crust2.0
Fit global dataset of dispersion maps (*Ritzwoller et al.,* 2002) using Monte Carlo



Top: Smooth Moho of SEMum2 (km); **Bottom**: SEM (*C=0.4*) time step (s)

=> SEM time step prolonged 4 times

1st generation upper mantle model: SEMum

- Full waveforms, T> 60 s, 200 events
- Replace realistic crust by a homogenized, smooth radially anisotropic crustal model
 - Uniform thickness of 60 km
 - Made to fit a global surface wave group velocity dispersion data set (20-60 s)
- Radially anisotropic model
 - Vs (isotropic shear velocity)
 - $\xi = (Vsh/Vsv)^2$
- Upper mantle only:
 - Lower mantle from existing tomographic model SAW24B16

Start with 1D model

As iterations progress:

- Progressively add waveforms as model improves
- Add 3D radial anisotropy at 3rd iteration
- Refine model parametrization
 - -> 642 to 2562 spherical spline nodes in Vs
 - -> 162 to 642 nodes for ξ
- Recalculate kernels at each iteration (non-linear)
- After 10 iterations-> SEMum

2nd generation model SEMum2

- Replace 60 km crust by variable Moho homogeneized crust (designed to fit same group velocity dataset)
- Introduce modified crustal corrections to account for strong non-linearity in NACT
- 2 iterations beyond SEMum
 Additional waveforms get included

French et al., 2012



SEMum2: 204 events ~ 100,000 wavepackets







SEMum2.2 model structure



(Ages from Muller, et al. 2009, G³)





Geographic extent of oceanic region OR2 in clustering analysis of SEMum with N=6, and the location of major hotspots



SEMum2.2 model structure Continental example region: Africa 20.0W, 25.0N to 45.0E, 10.0S (dlnVs -5.270/+8.806) SW NE Depth (km) 200 300



Conclusions

- SEMum2 shows similar large scale features in good agreement with previous global models developed using "approximate" theory
- Subduction zones better resolved, approaching resolution of recent P models (e.g. Fukao and Obayashi, 2011)
- Continental roots are well marked, max. depth 200-250 km
- SEMum2 exhibits significantly stronger low velocity regions:

Upper mantle low velocity zone

- Well developed and strong LVZ in the oceans
- Depth of velocity minimum increases with age
- Velocity minimum in agreement with local study at EPR (in depth and strength)
- Bottom of LVZ well marked in general
- Deeper zone of low velocities (~250 km depth) forming "streaks" that appear to align with APM in Pacific
- Between 300 -800 km, columnar low velocity features associated with hotspots, but not necessarily with single hotspot, and can be offset horizontally

Outlook

 Our modeling confirms common wisdom that more exact theory can resolve low velocity structures better

Only beginning - next steps:
– Perform source perturbations
– Shorter periods (40 s) ->
• Lower mantle
• Higher resolution
– Upper mantle attenuation (Jamie Barron's

poster)