



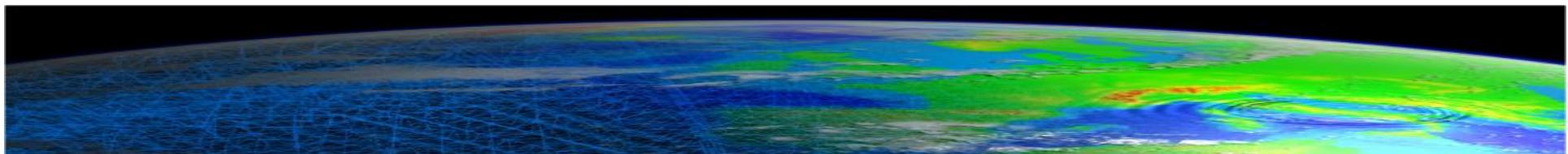
Finite source model determinations for large magnitude earthquakes using long-period normal mode data

K. Lentas⁽¹⁾, A. M. G. Ferreira⁽¹⁾, M. Vallée⁽²⁾, E. ClévéDé⁽³⁾

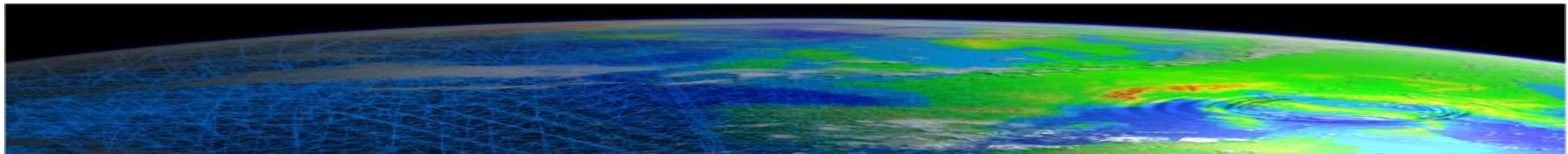
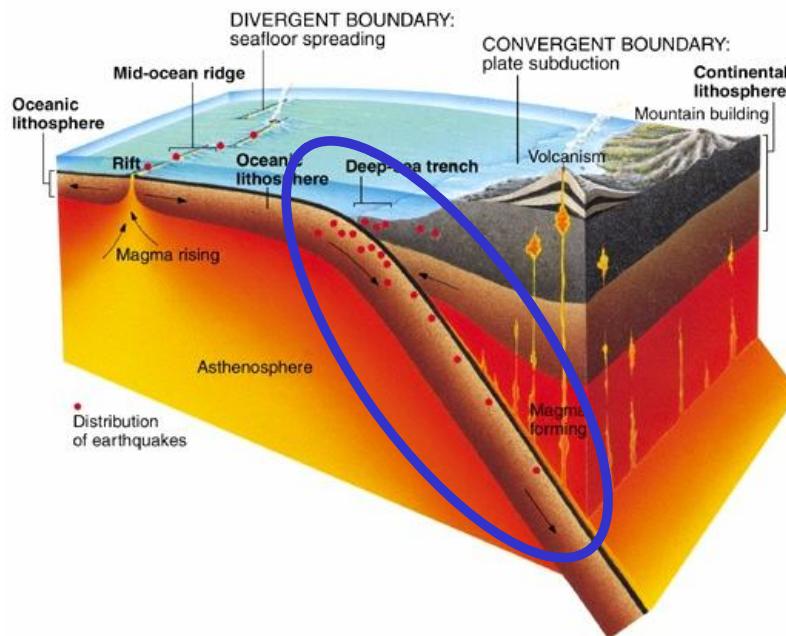
⁽¹⁾School of Environmental Sciences, University of East Anglia, Norwich, UK

⁽²⁾Géoazur, IRD, Nice, France

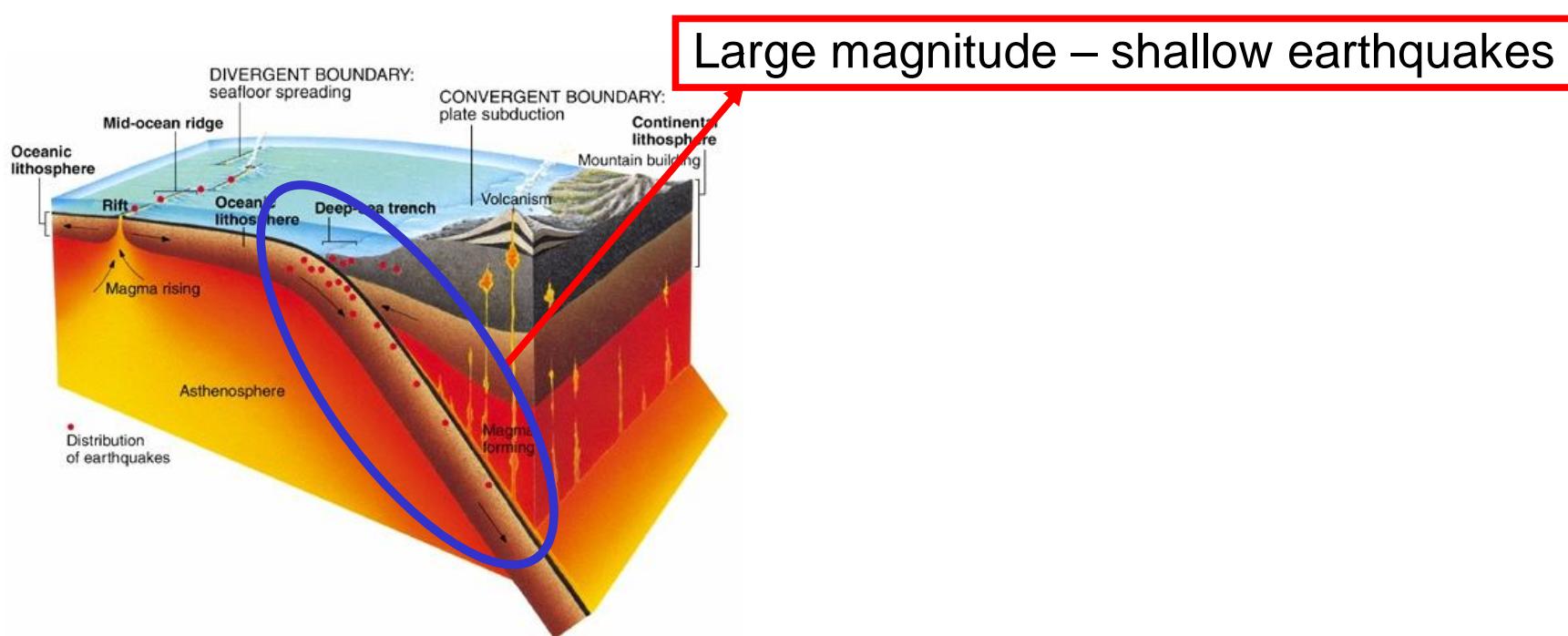
⁽³⁾Institut du Globe de Physique, Paris, France



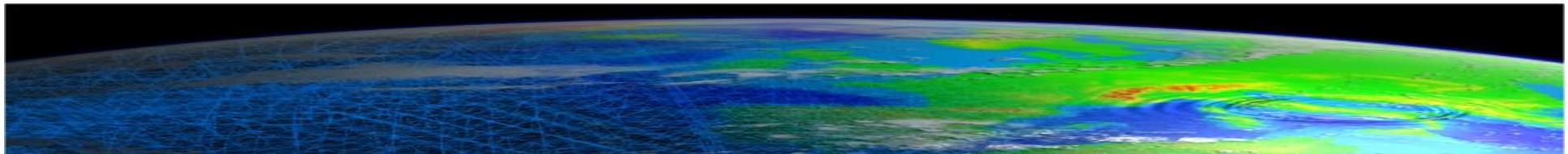
Goal and motivation



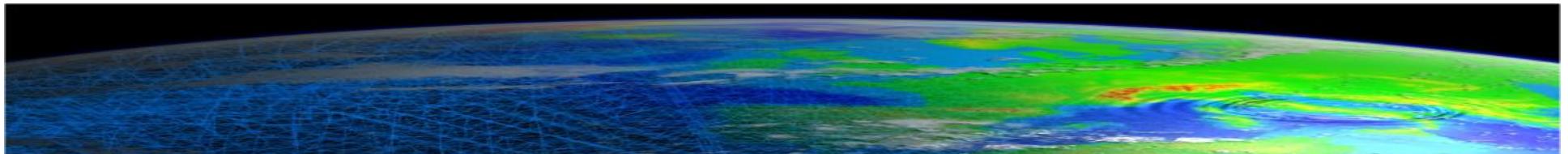
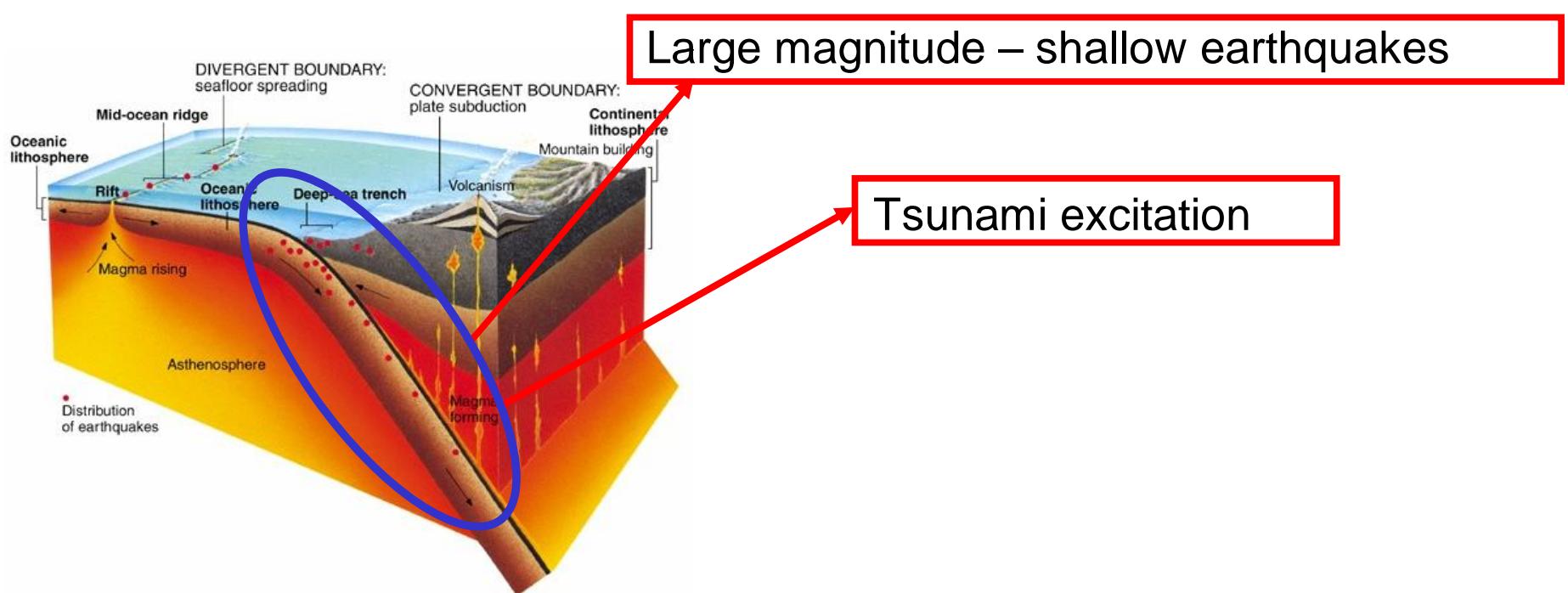
Goal and motivation



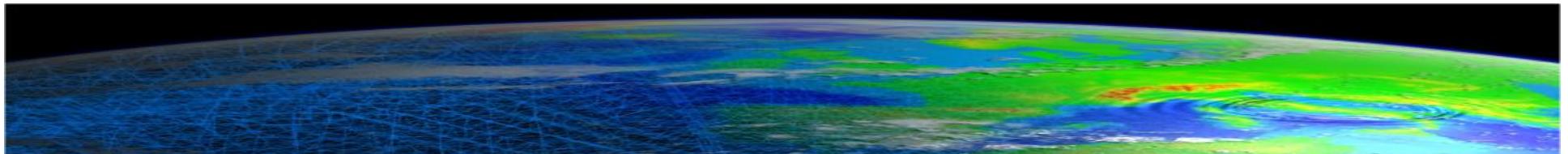
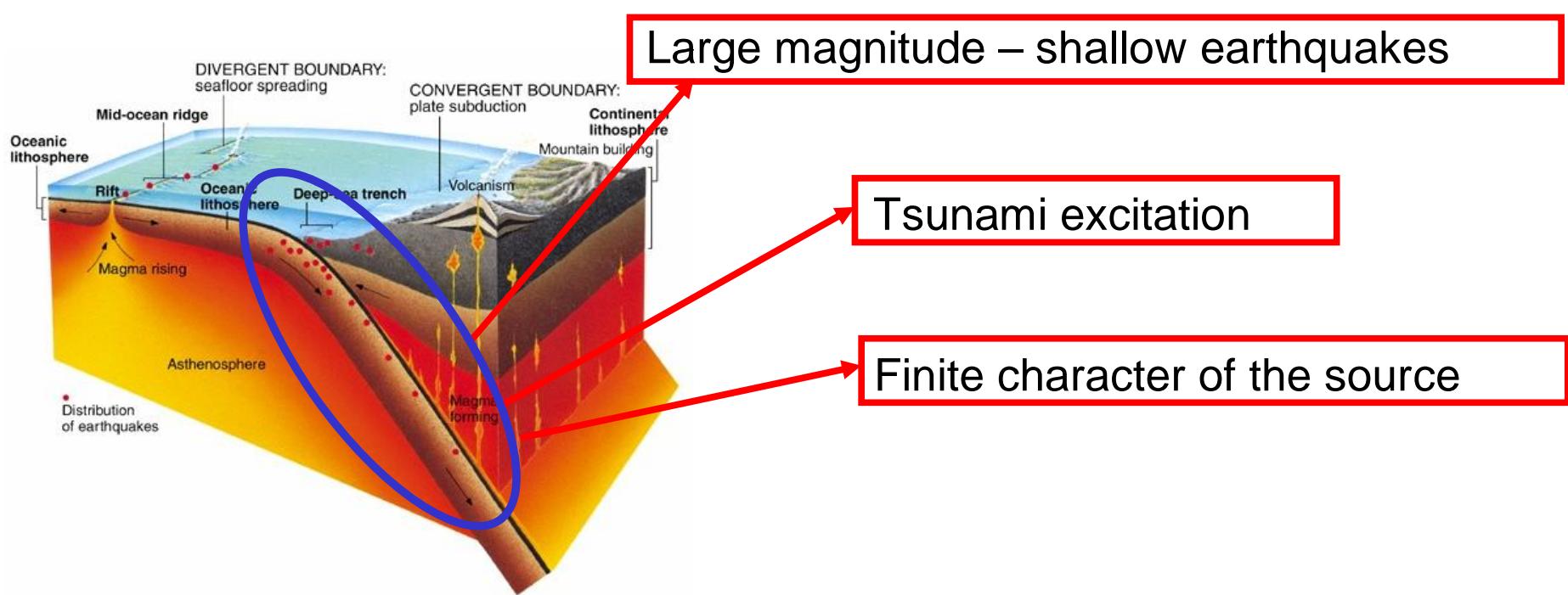
Large magnitude – shallow earthquakes



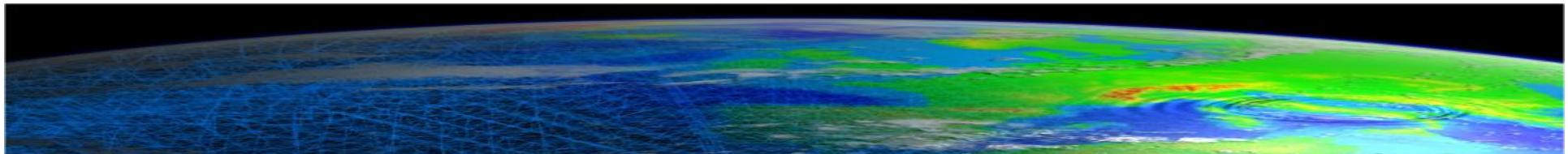
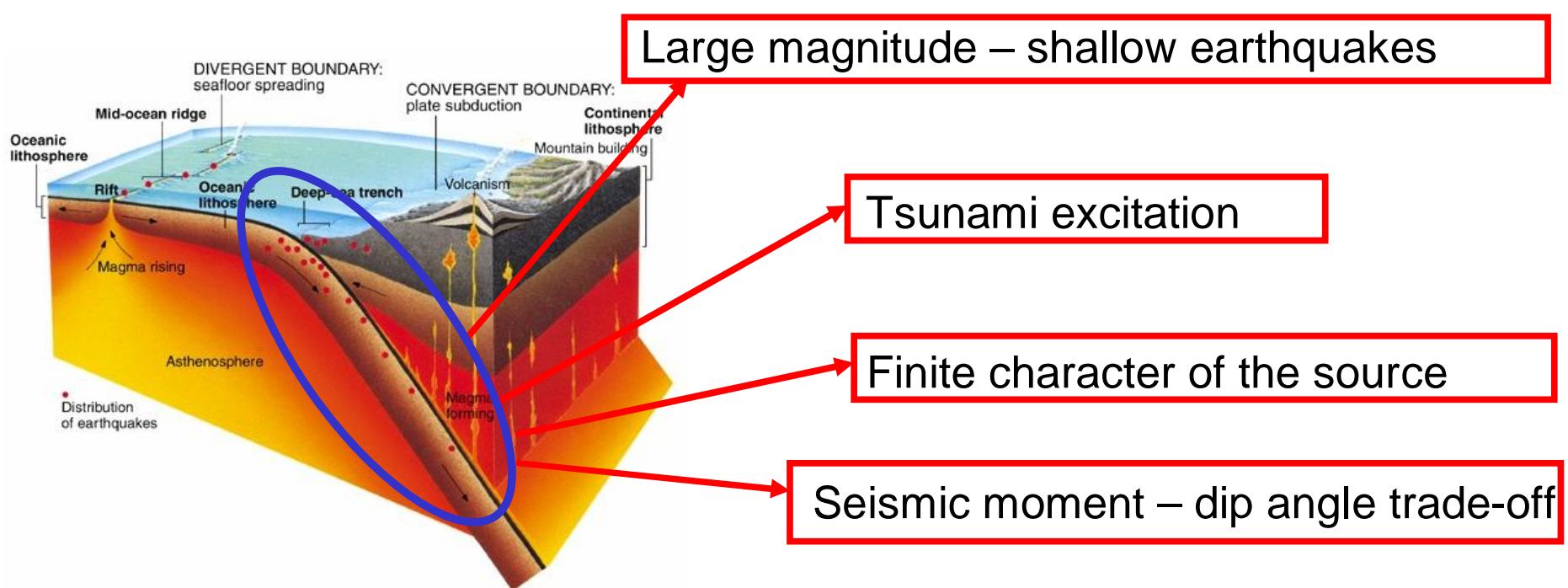
Goal and motivation



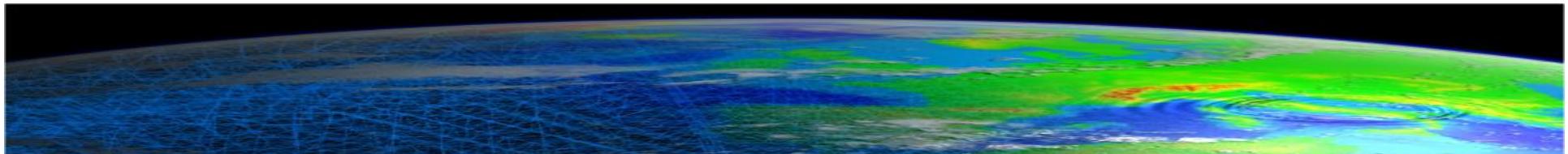
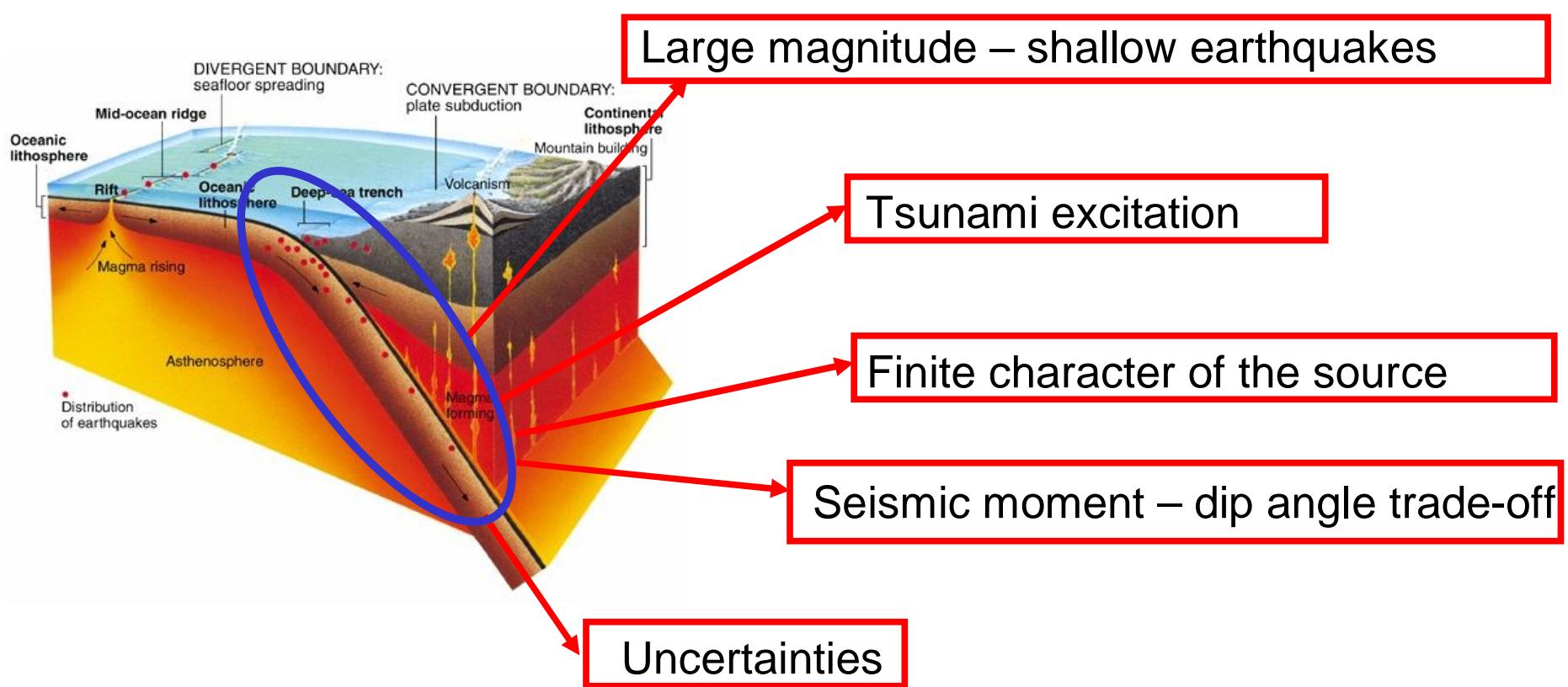
Goal and motivation



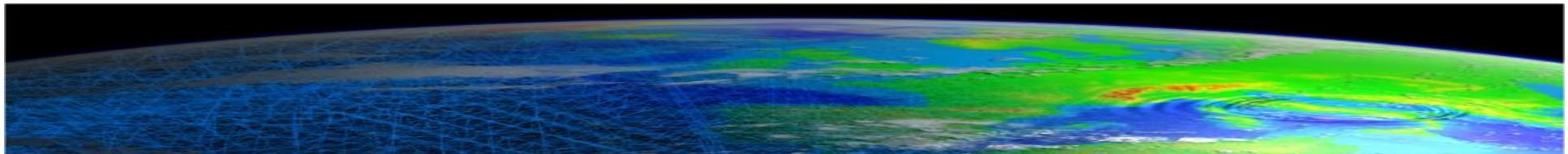
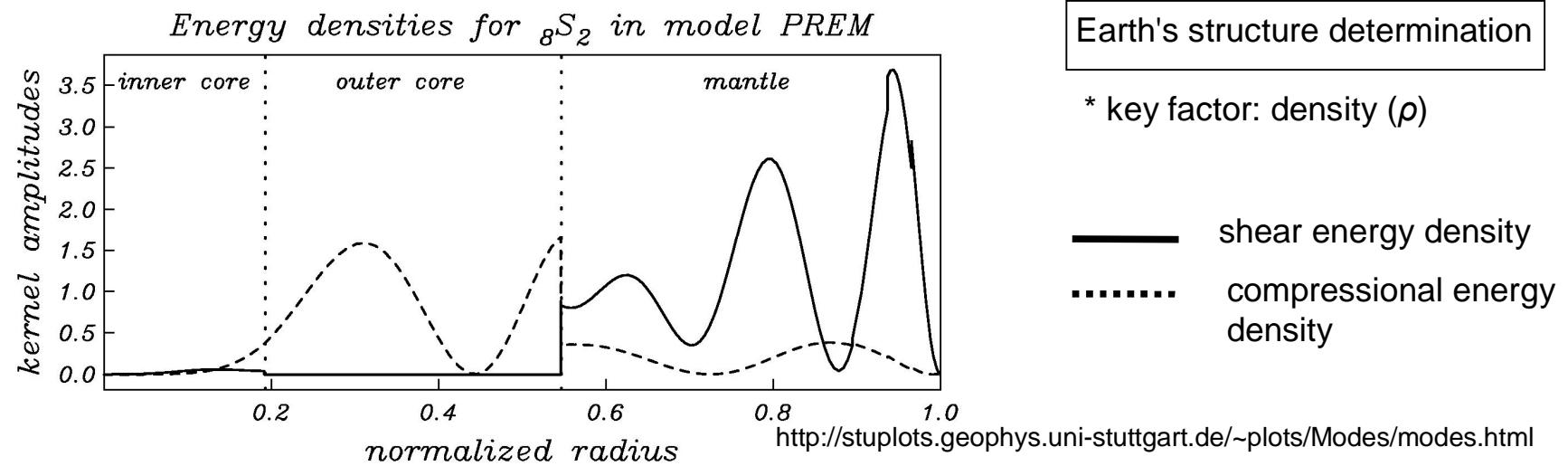
Goal and motivation



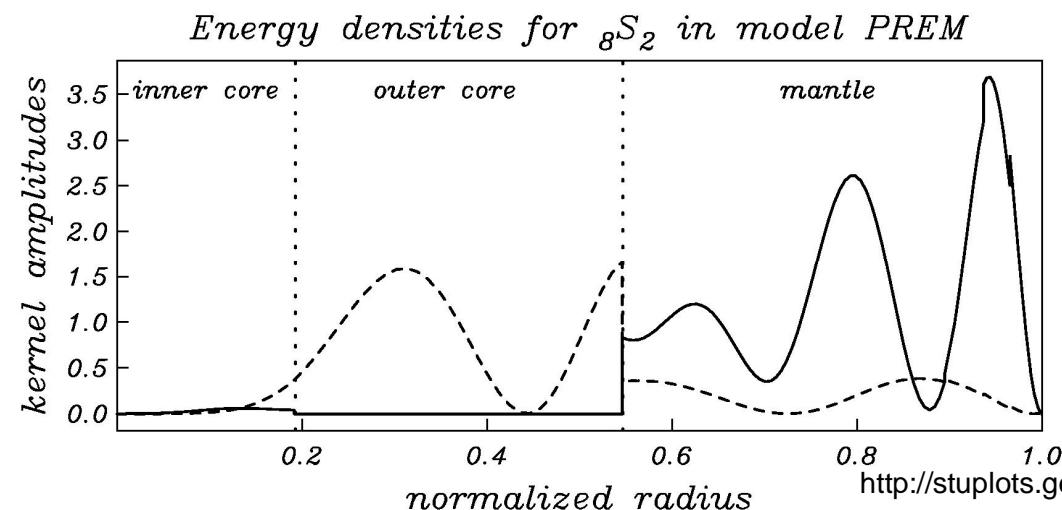
Goal and motivation



Goal and motivation



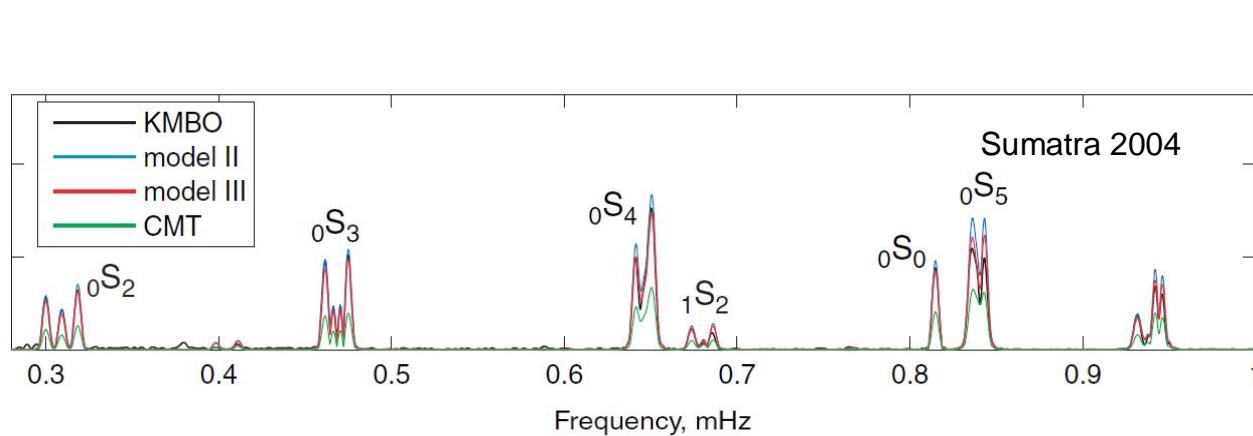
Goal and motivation



Earth's structure determination

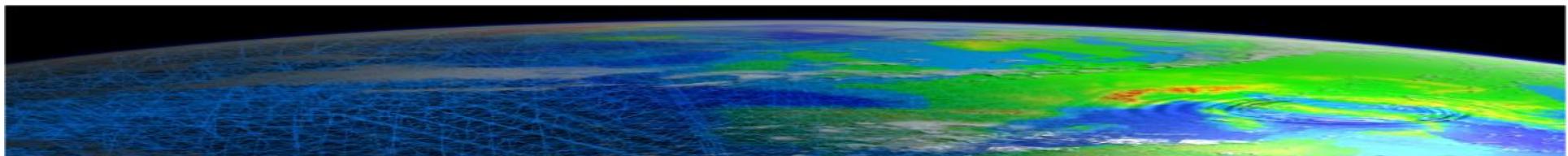
* key factor: density (ρ)

— shear energy density
- - - - compressional energy density

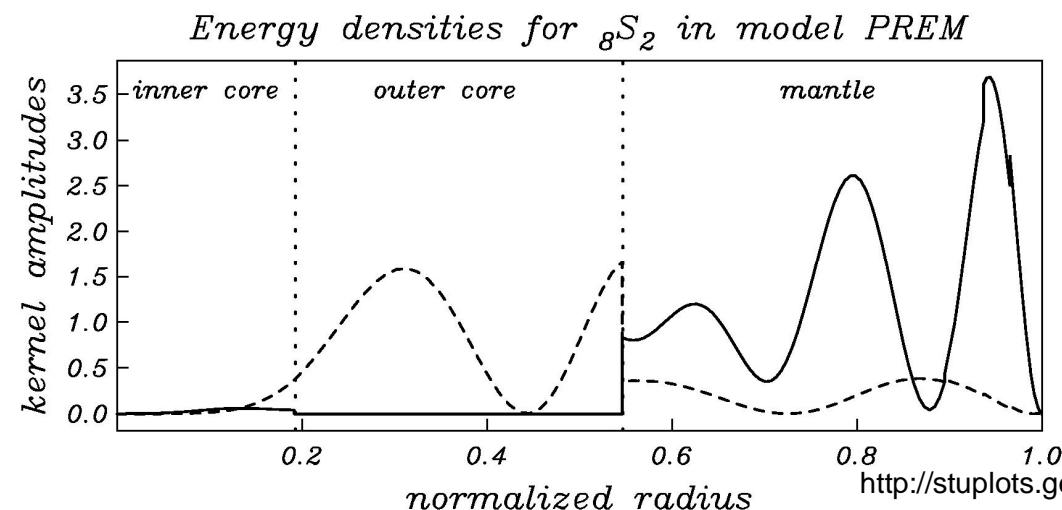


Earthquake source studies

Park et al., (2005)



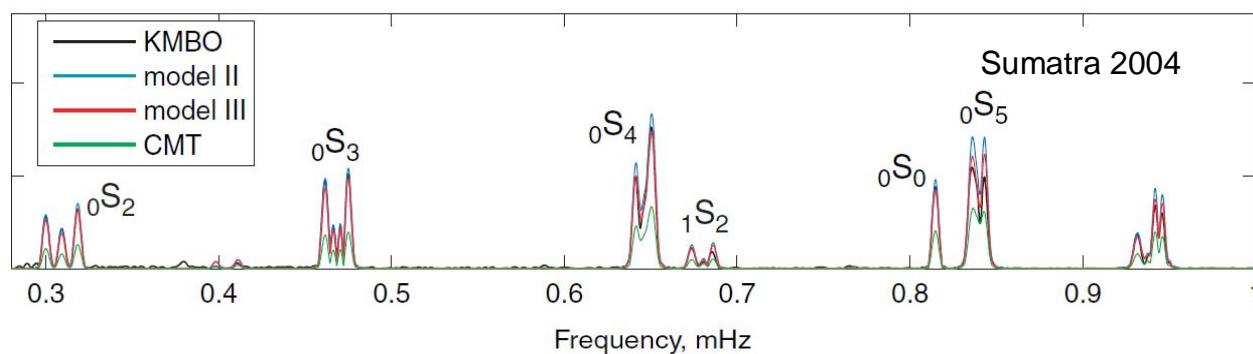
Goal and motivation



Earth's structure determination

* key factor: density (ρ)

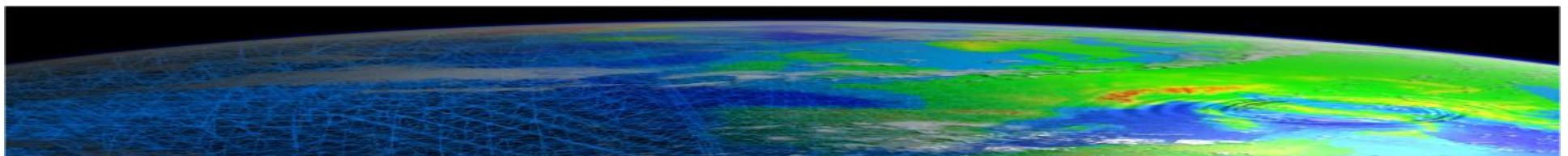
— shear energy density
- - - - compressional energy density



Earthquake source studies

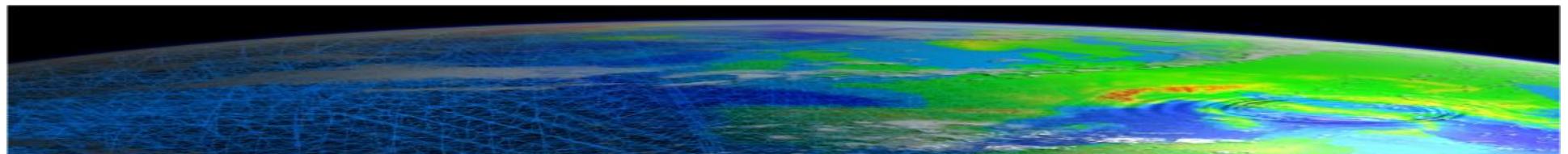
SOURCE MODEL DETERMINATION USING NORMAL MODES

Park et al., (2005)



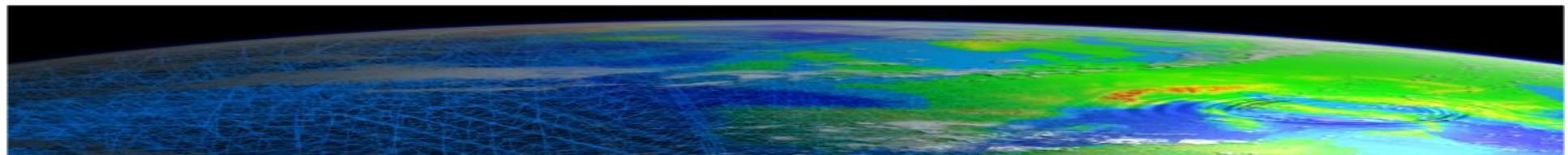
Summary

1. Testing existing global subduction earthquake source models
2. Probabilistic normal mode source model inversion



Summary

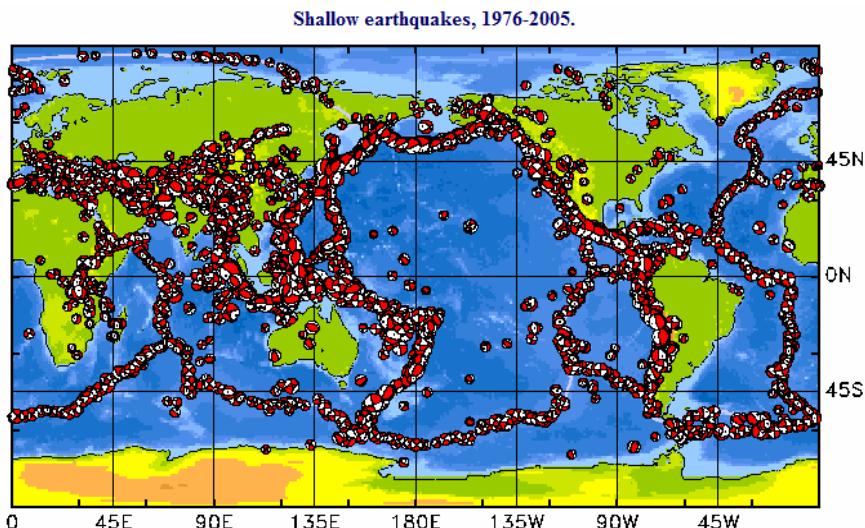
1. Testing existing global subduction earthquake source models
2. Probabilistic normal mode source model inversion



1. Source model validation tests

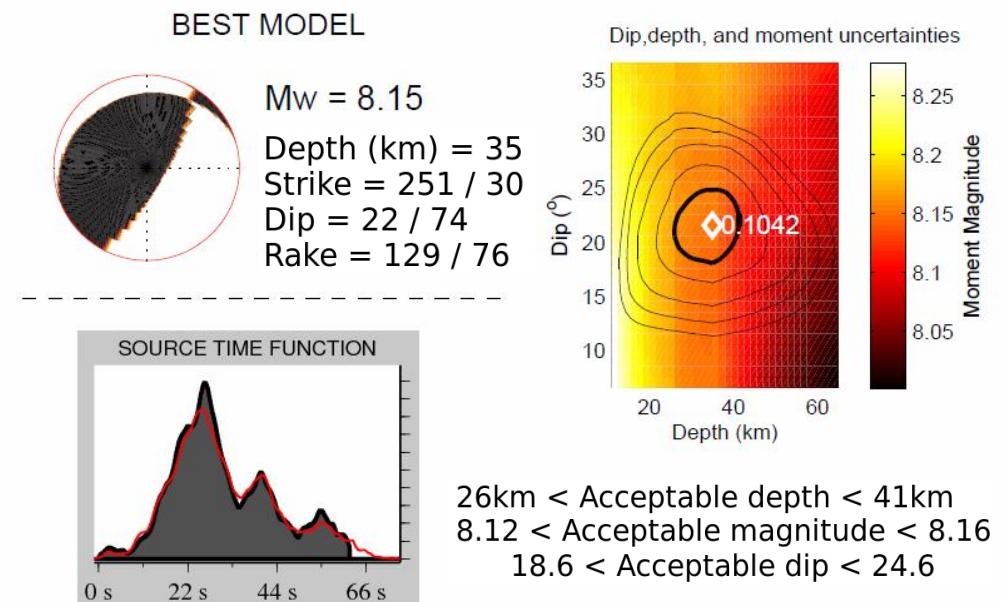
The GCMT and SCARDEC methods

- Semi-automated technique
- Long-period body-wave & surface-wave data (45 - 135 s)
- Point source approximation (centroid location)
- Time needed > 3h



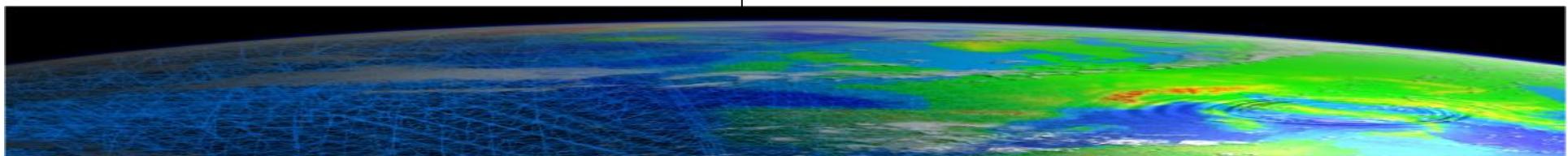
<http://www.globalcmt.org/>

- Automated technique
 - Long-period body-wave data (33 - 200 s)
 - Point source parameters & STF
 - No location determination
 - Time needed ~ 40 min
- 20030925_Hokkaido_



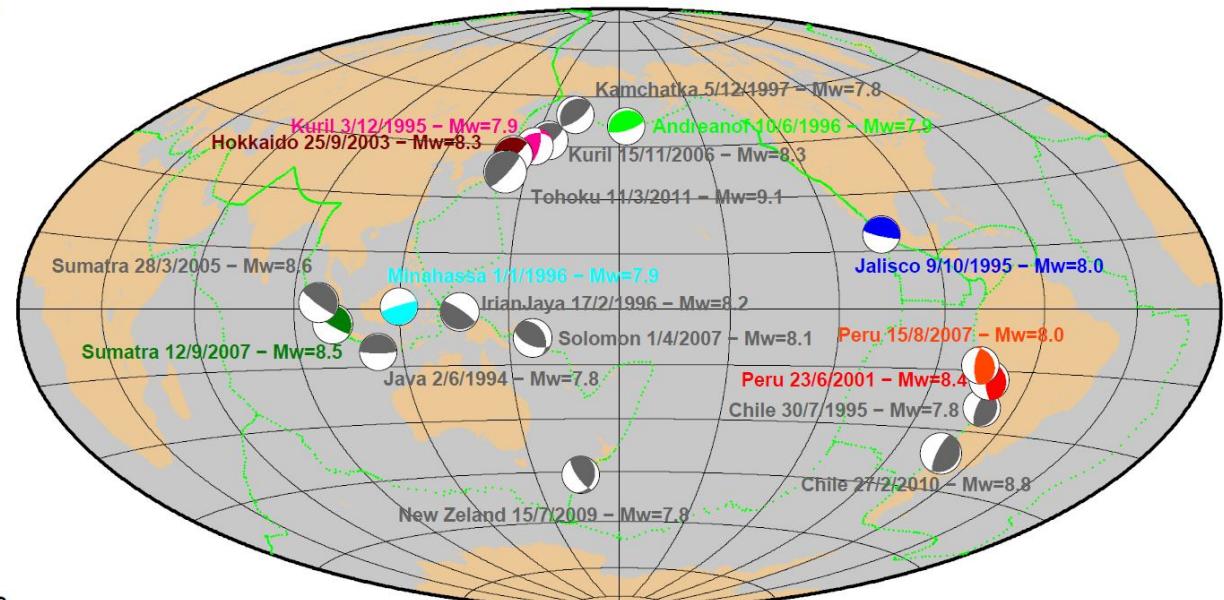
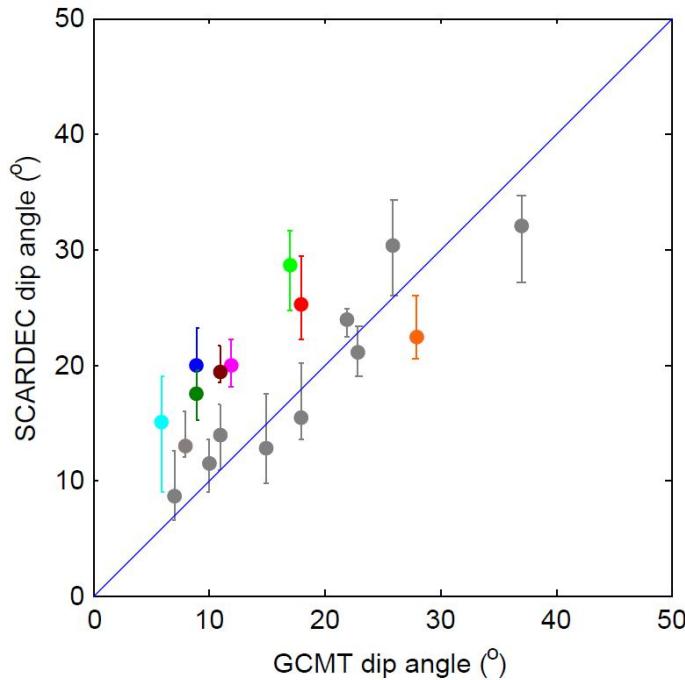
<http://geoazur.oca.eu/SCARDEC>

Vallée et al., (2010)



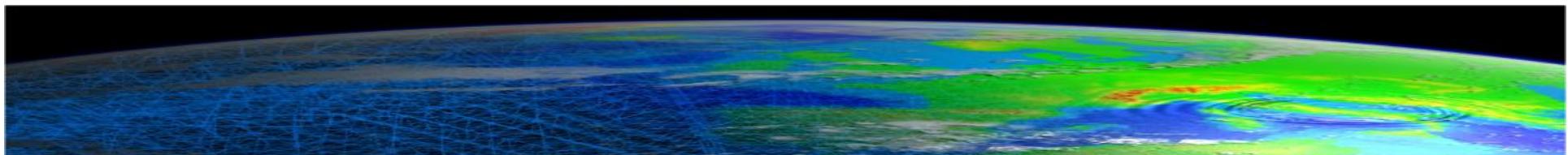
1. Source model validation tests

Subduction earthquakes studied



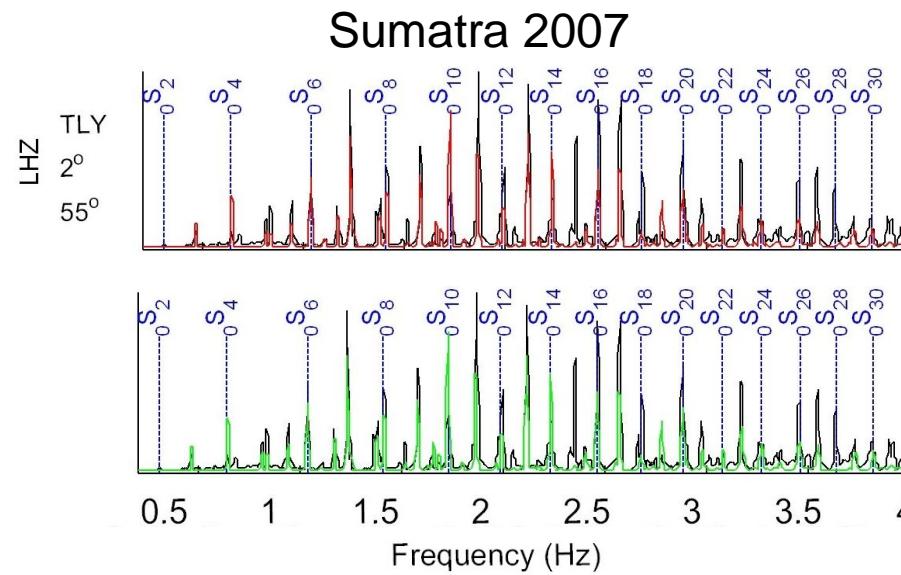
- $M_w \geq 7.8$ subduction zone earthquakes over the last 20 years (Vallée et al., 2010)
- 8 selected earthquakes having large differences between GCMT and SCARDEC ($\Delta\delta_i \geq \Delta\delta_{average}$)

Lentas, Ferreira and Vallée, 2012 (in prep.)

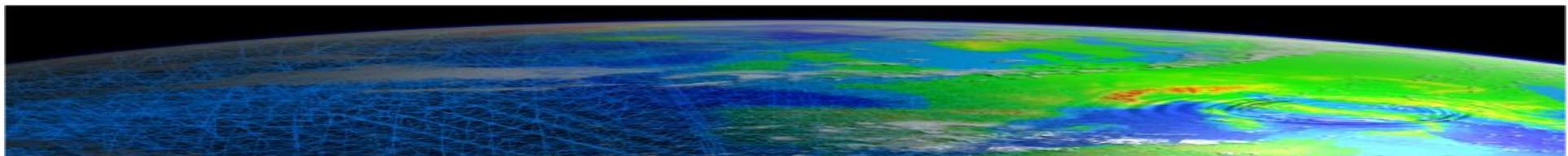
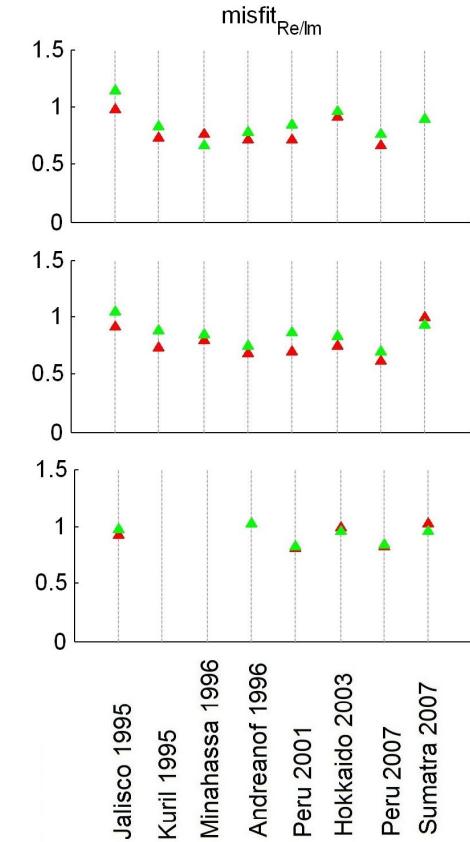
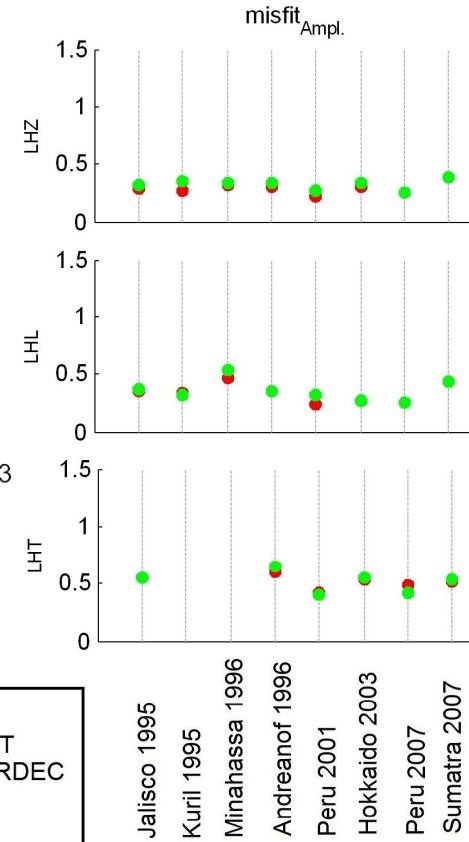
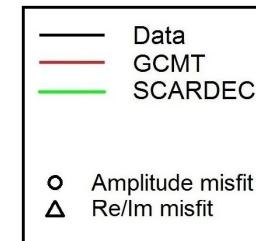
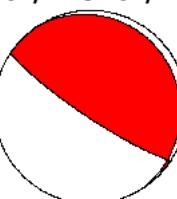
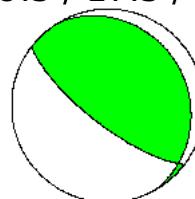


1. Source model validation tests

Normal mode spectra comparisons


 $\times 10^{-3}$

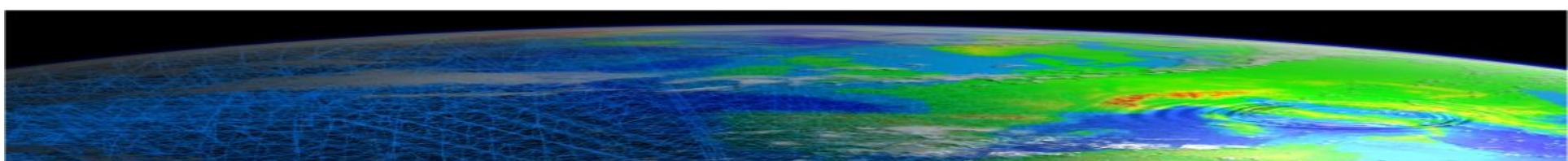
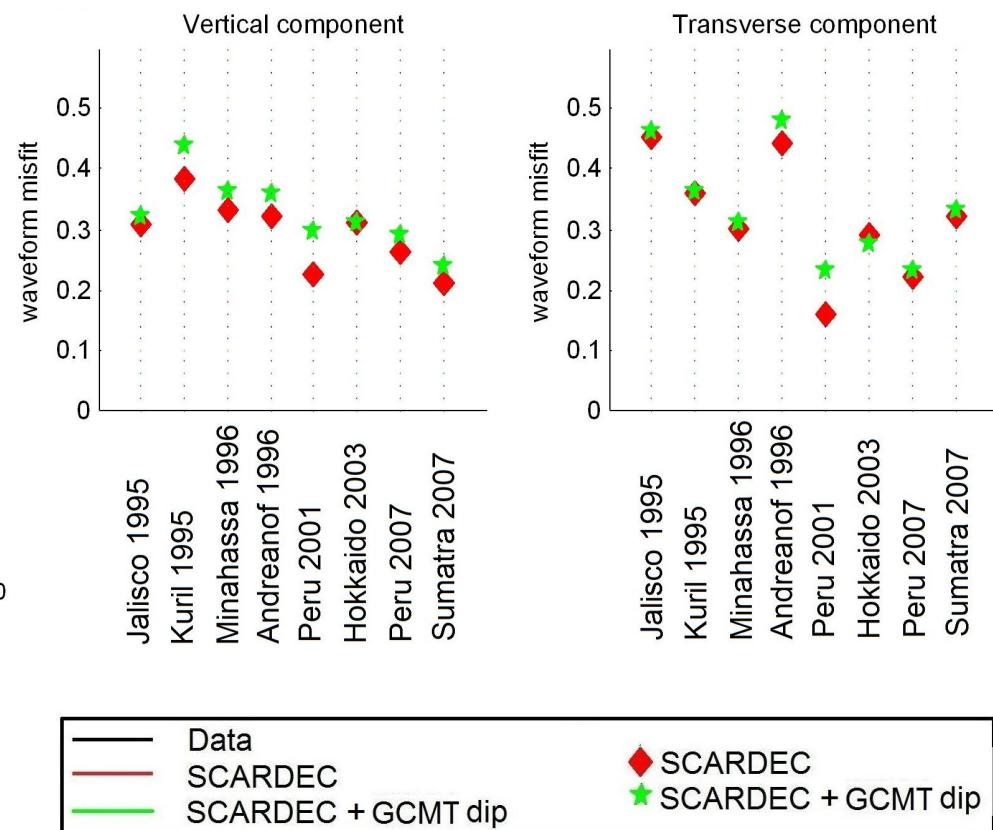
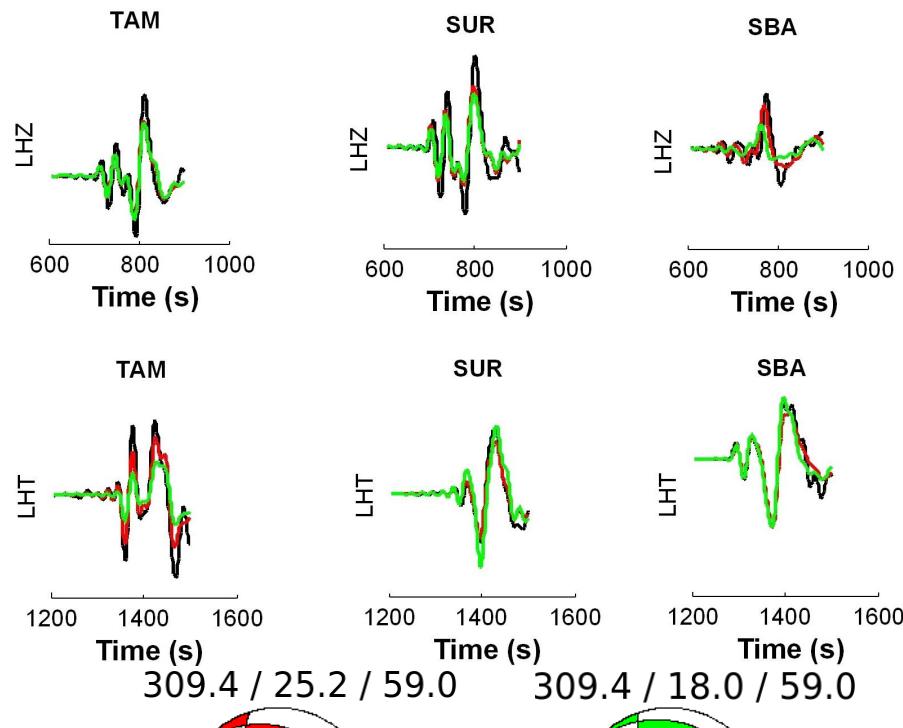
329.5 / 17.5 / 111.0 328.0 / 9.0 / 114.0



1. Source model validation tests

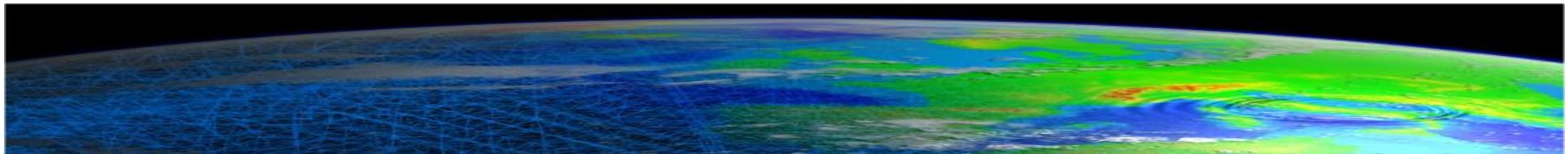
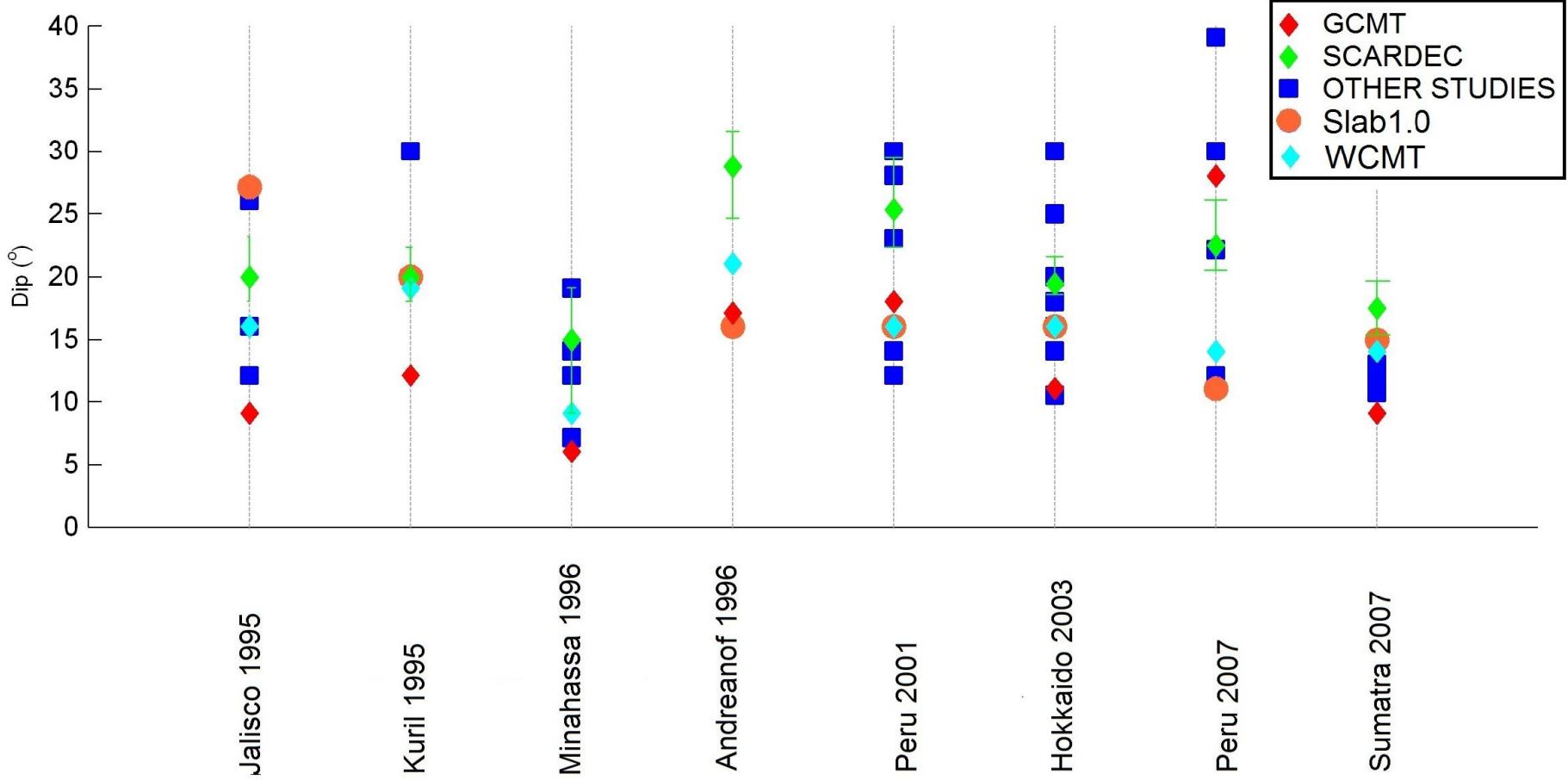
Body-wave comparisons

Peru 2001



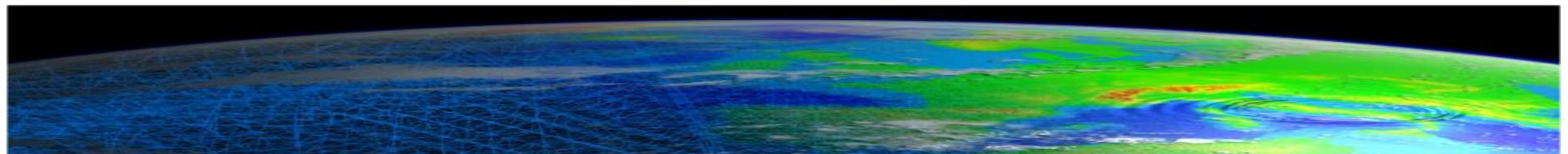
1. Source model validation tests

Comparisons with results taken from the literature



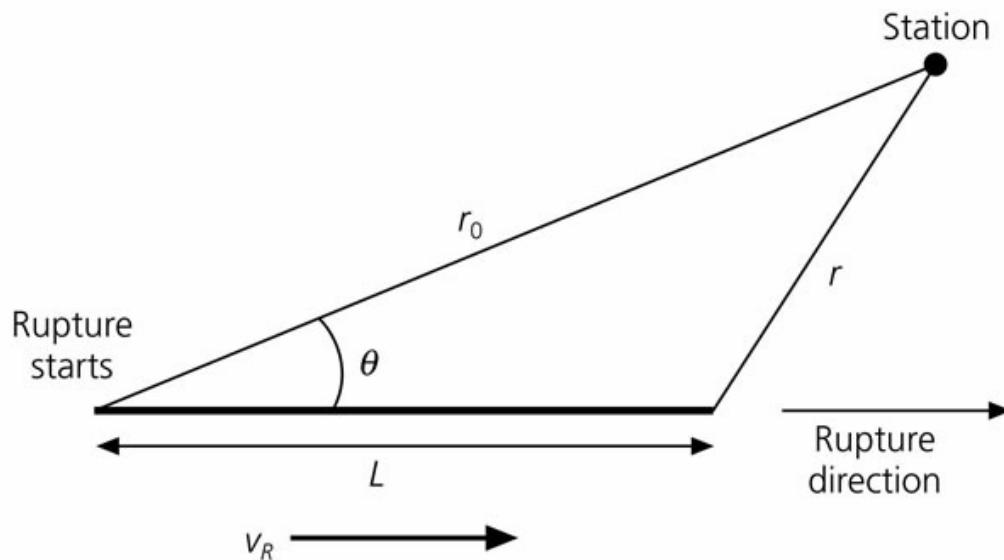
Summary

1. Testing existing global subduction earthquake source models
2. Probabilistic normal mode source model inversion



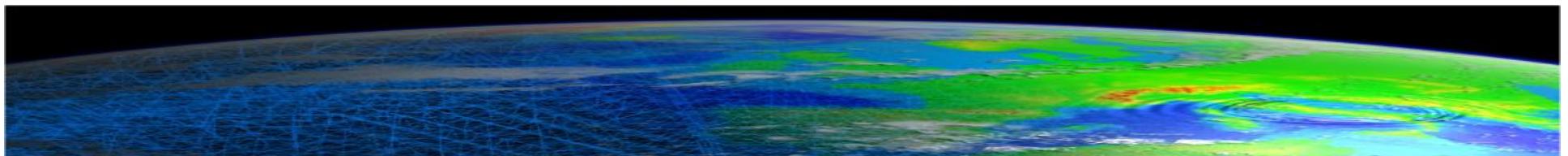
2. Normal mode source model inversion

Finite source description



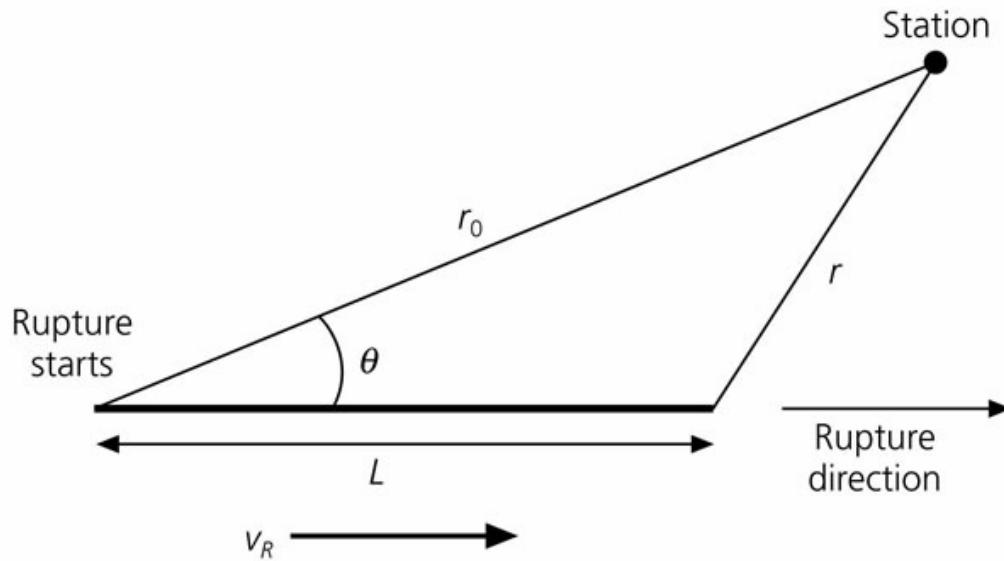
$$a_m^{fs}(x,t) = a_m^{ps}(x,t) * F_m$$

$$a_m^{fs}(x,\omega) = a_m^{ps}(x,\omega) \cdot F_m$$



2. Normal mode source model inversion

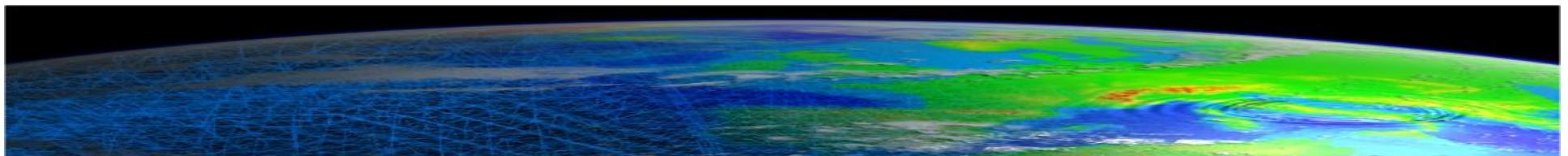
Finite source description



$$a_m^{fs}(x,t) = a_m^{ps}(x,t) * F_m$$

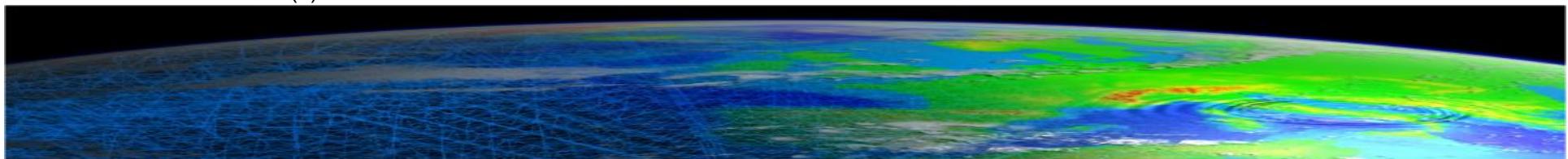
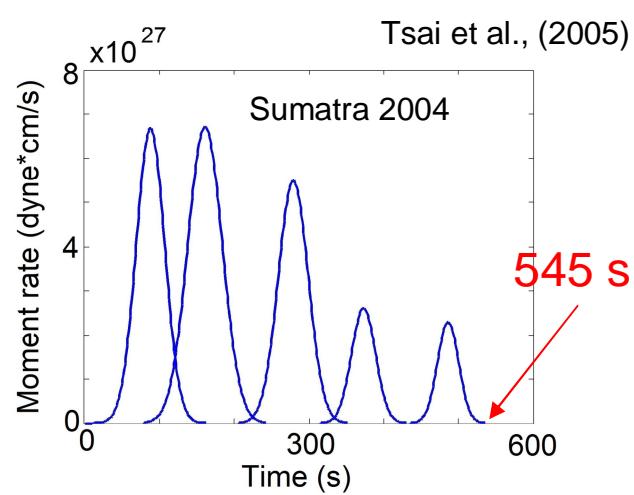
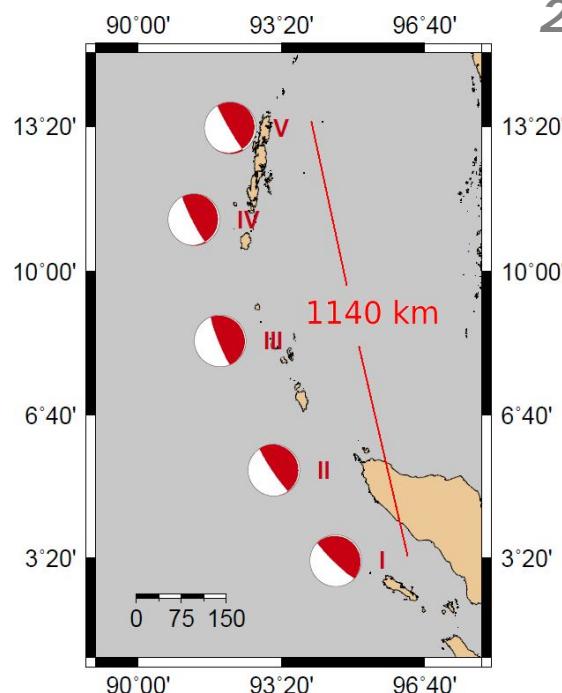
$$a_m^{fs}(x,\omega) = a_m^{ps}(x,\omega) \cdot F_m$$

$$x_m = f(L, T_r)$$



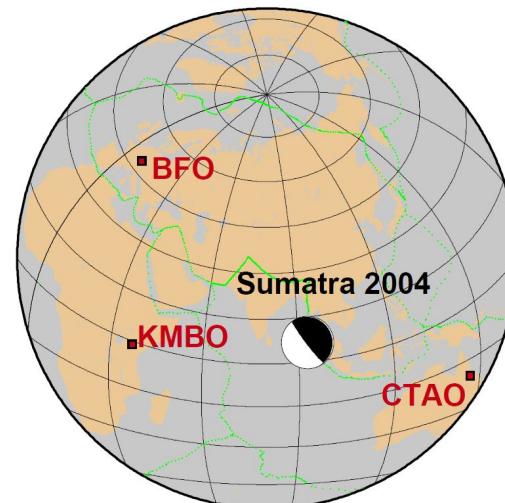
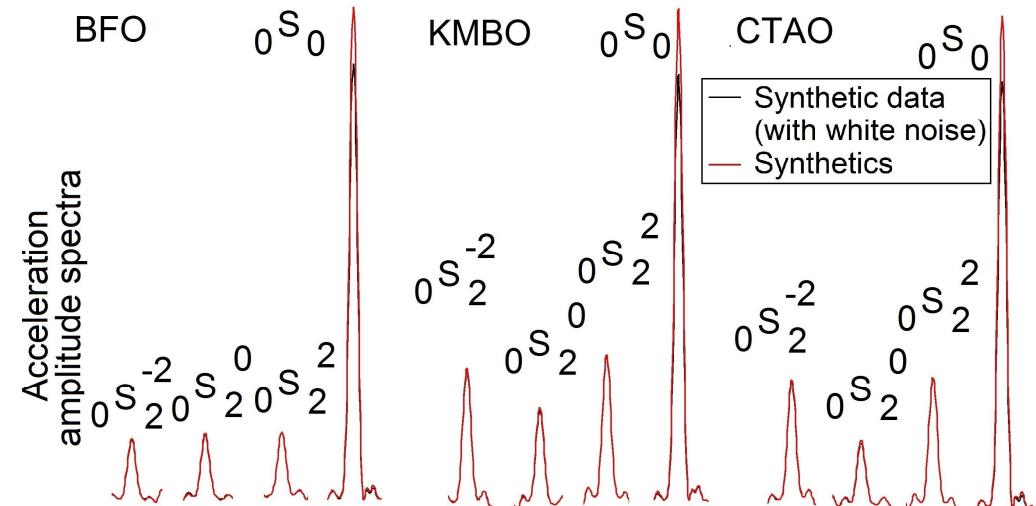
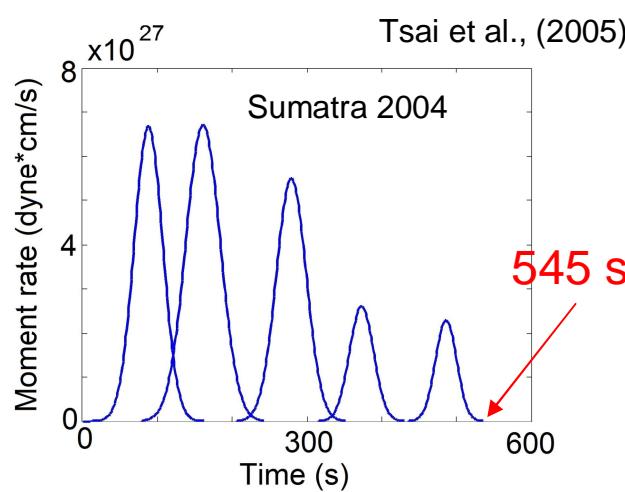
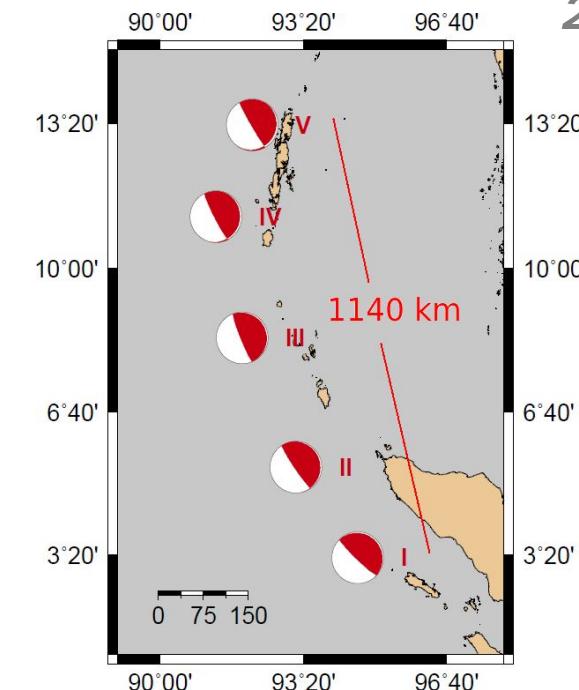
2. Normal mode source model inversion

Synthetic test



2. Normal mode source model inversion

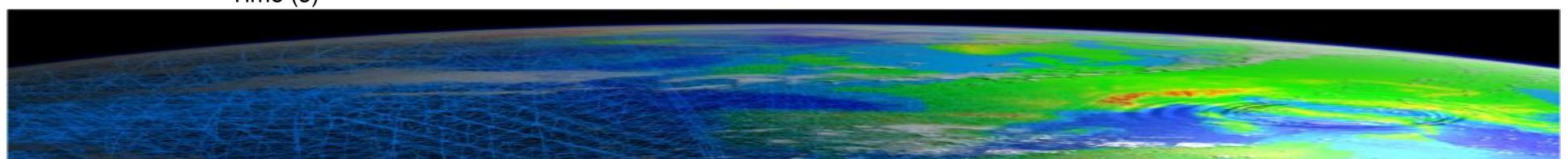
Synthetic test



$$L = 1158.2 \text{ km}$$

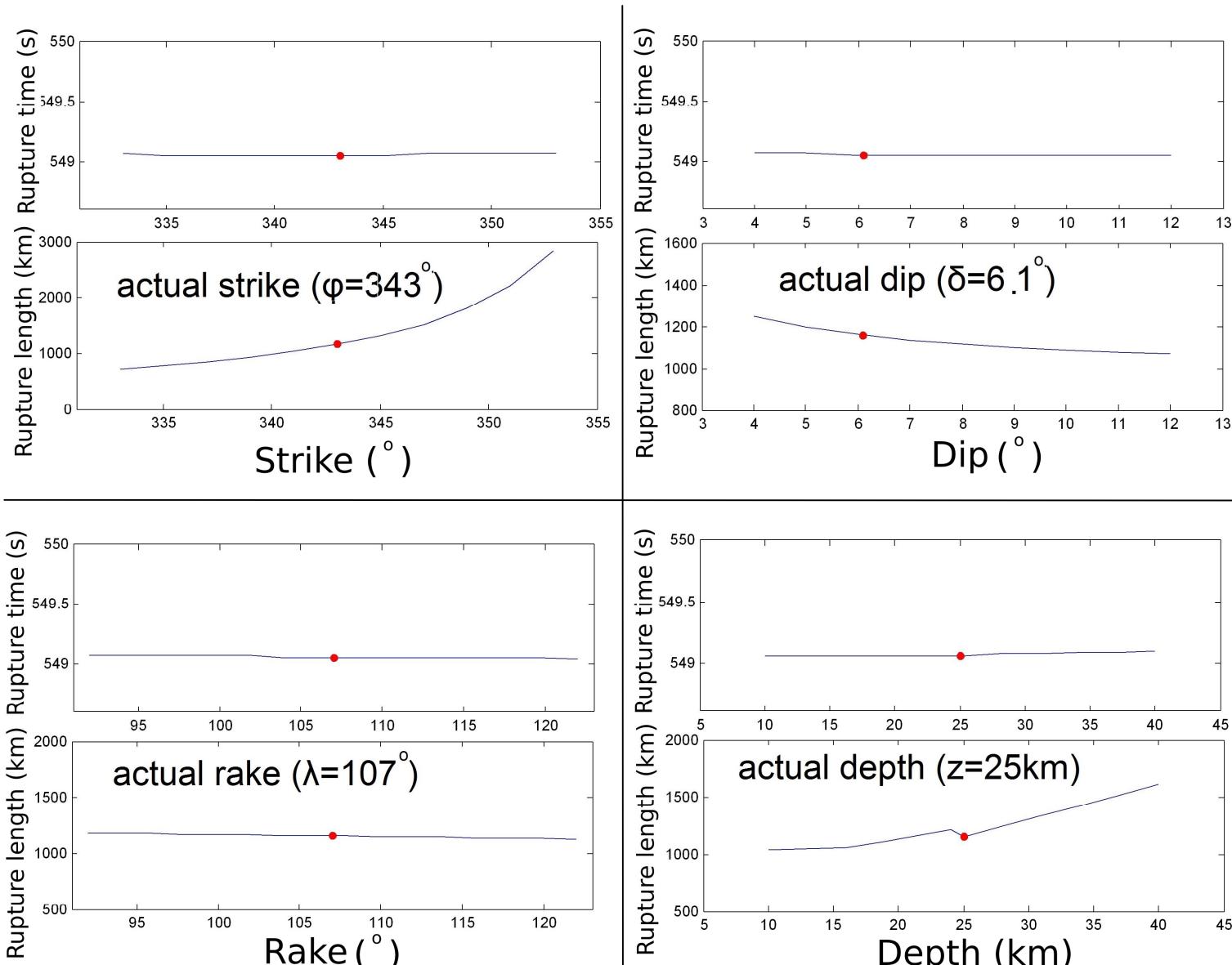
$$T_r = 549.1 \text{ sec}$$

$$V_r = 2.1 \text{ km/sec}$$



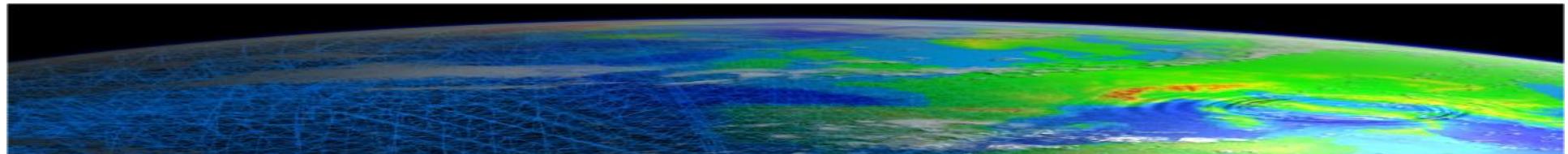
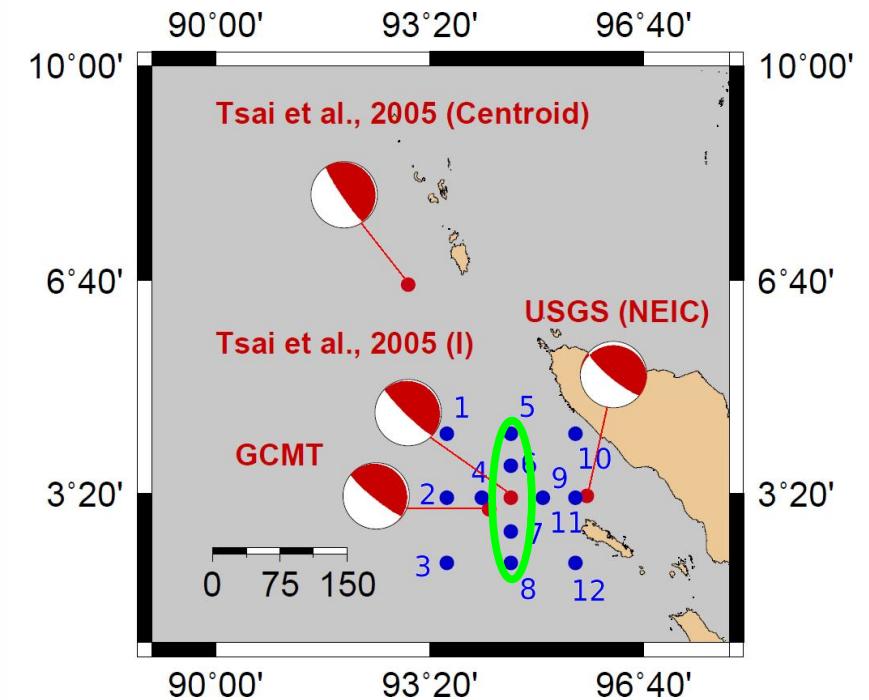
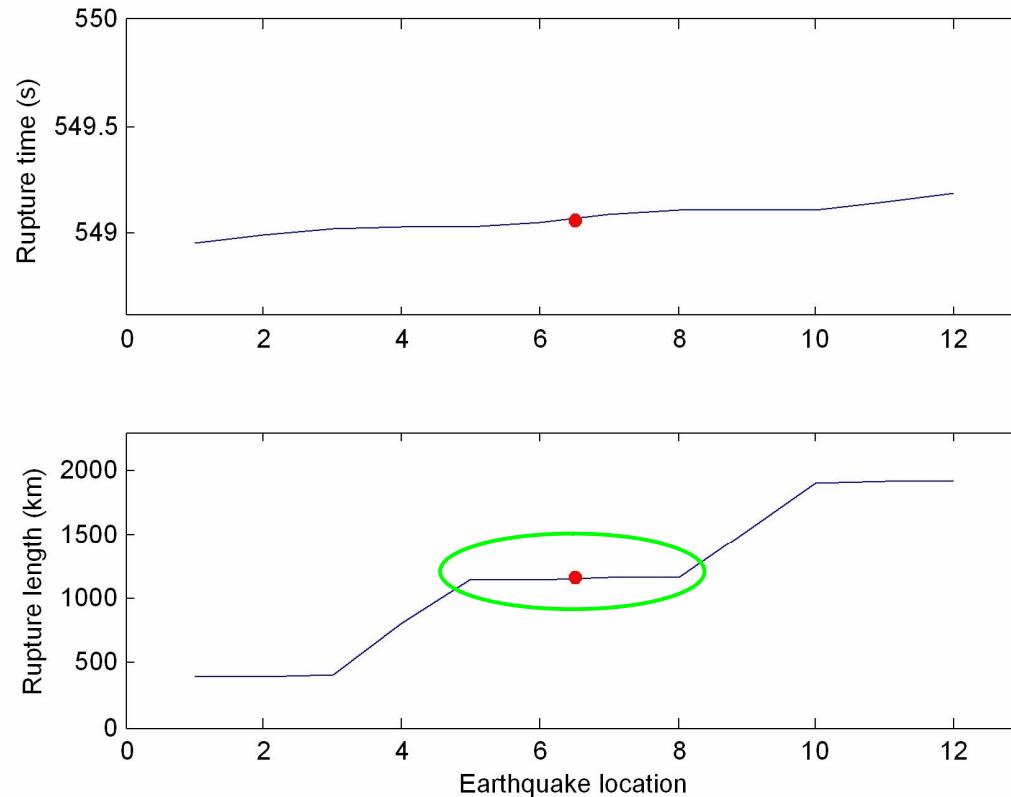
2. Normal mode source model inversion

Sensitivity of the inversion to source parameters



2. Normal mode source model inversion

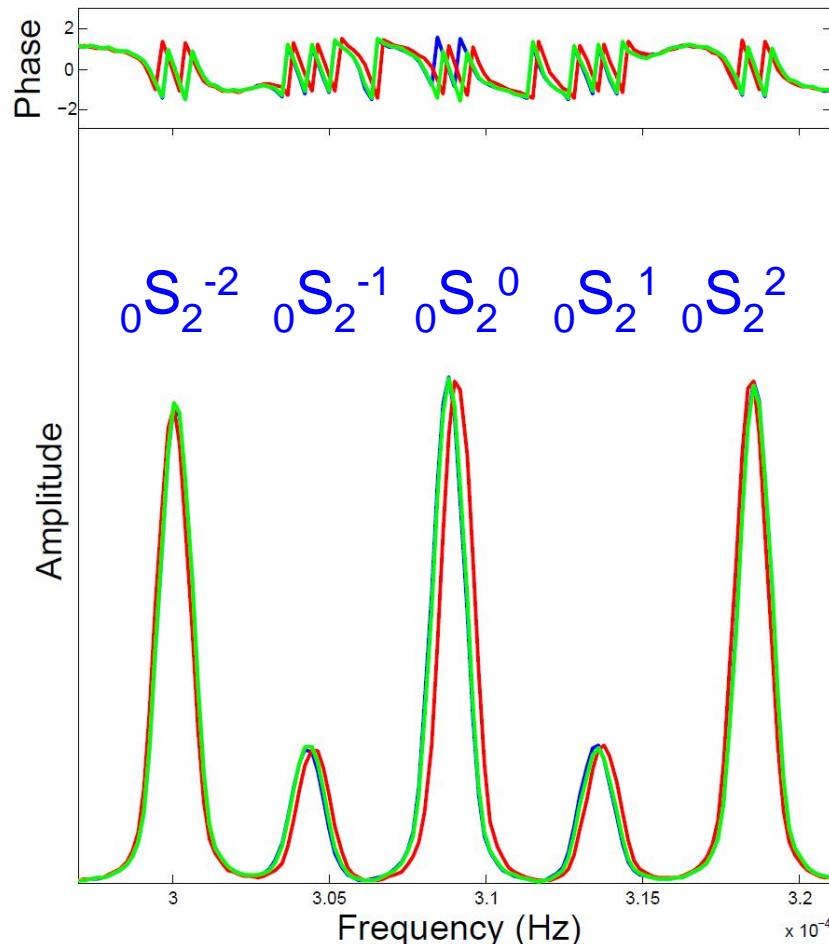
Sensitivity of the inversion to location



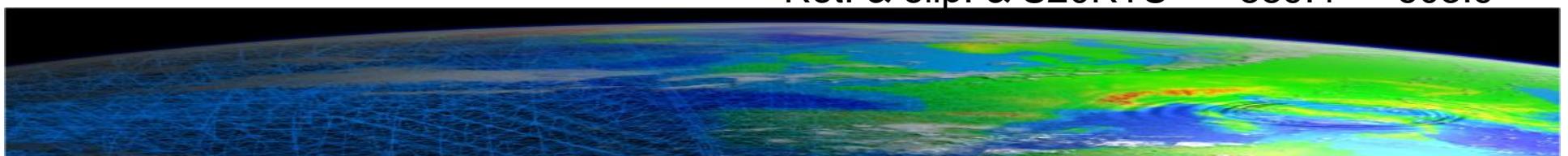
2. Normal mode source model inversion

Sensitivity of the inversion to the Earth's structure

480 hours acceleration spectra (BFO)

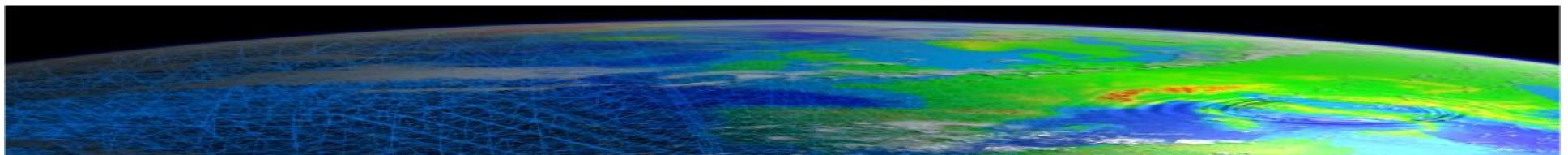
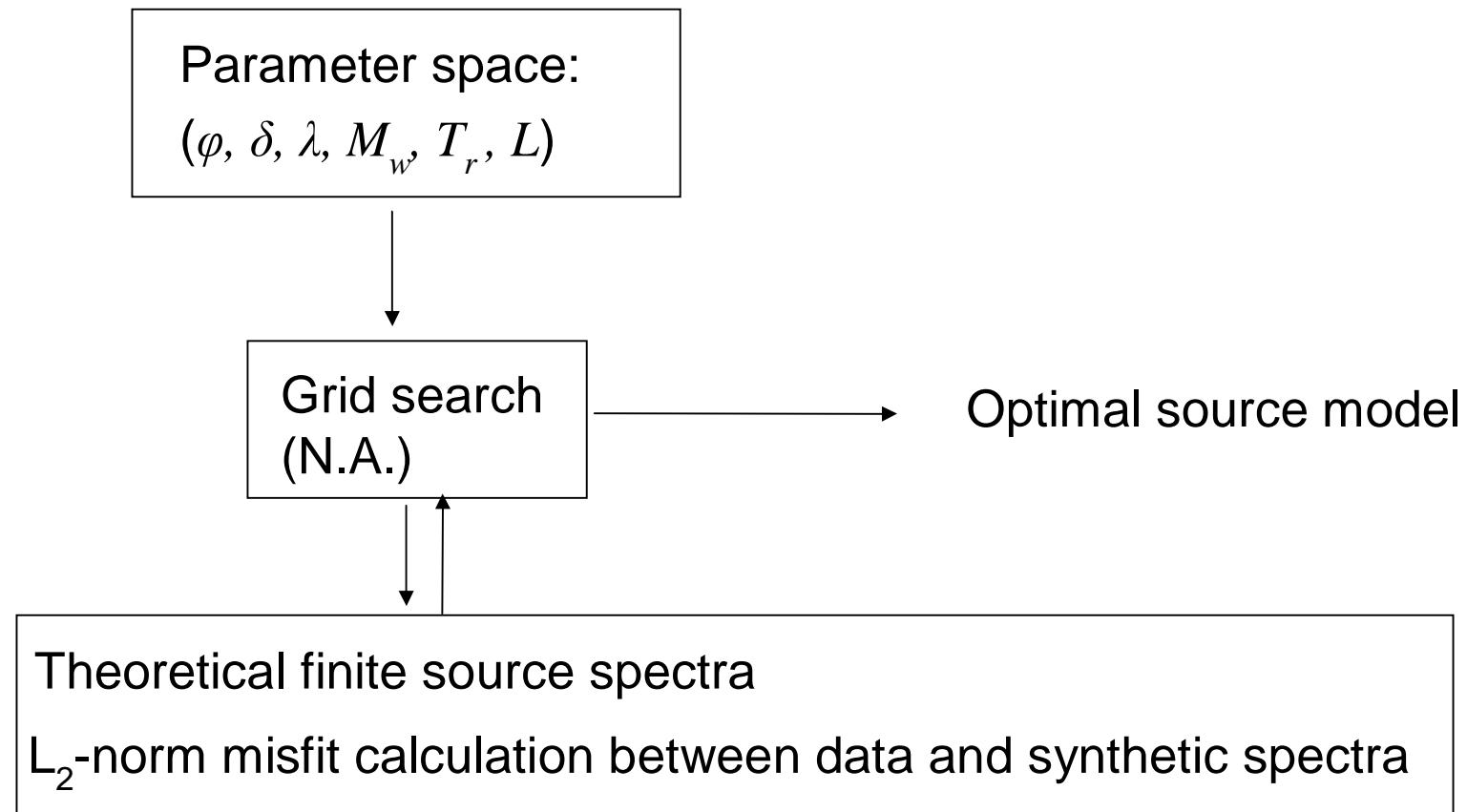


	$L(km)$	$T_r(s)$
Tsai et al., (2005)	1140.0	545.0
Rot. & elip. & SAW12D	1158.2	549.1
Rot. & elip. & PREM	1188.0	507.9
Rot. & elip. & S20RTS	889.4	603.9



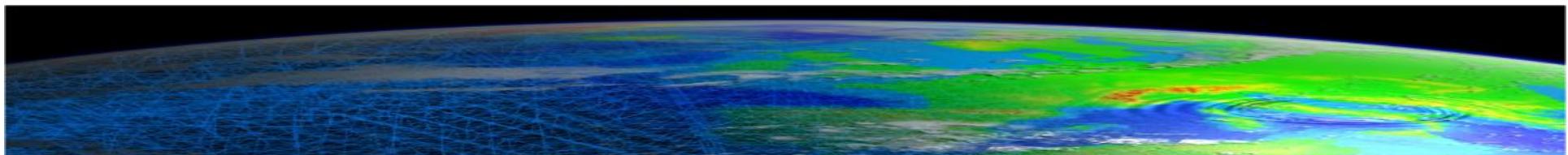
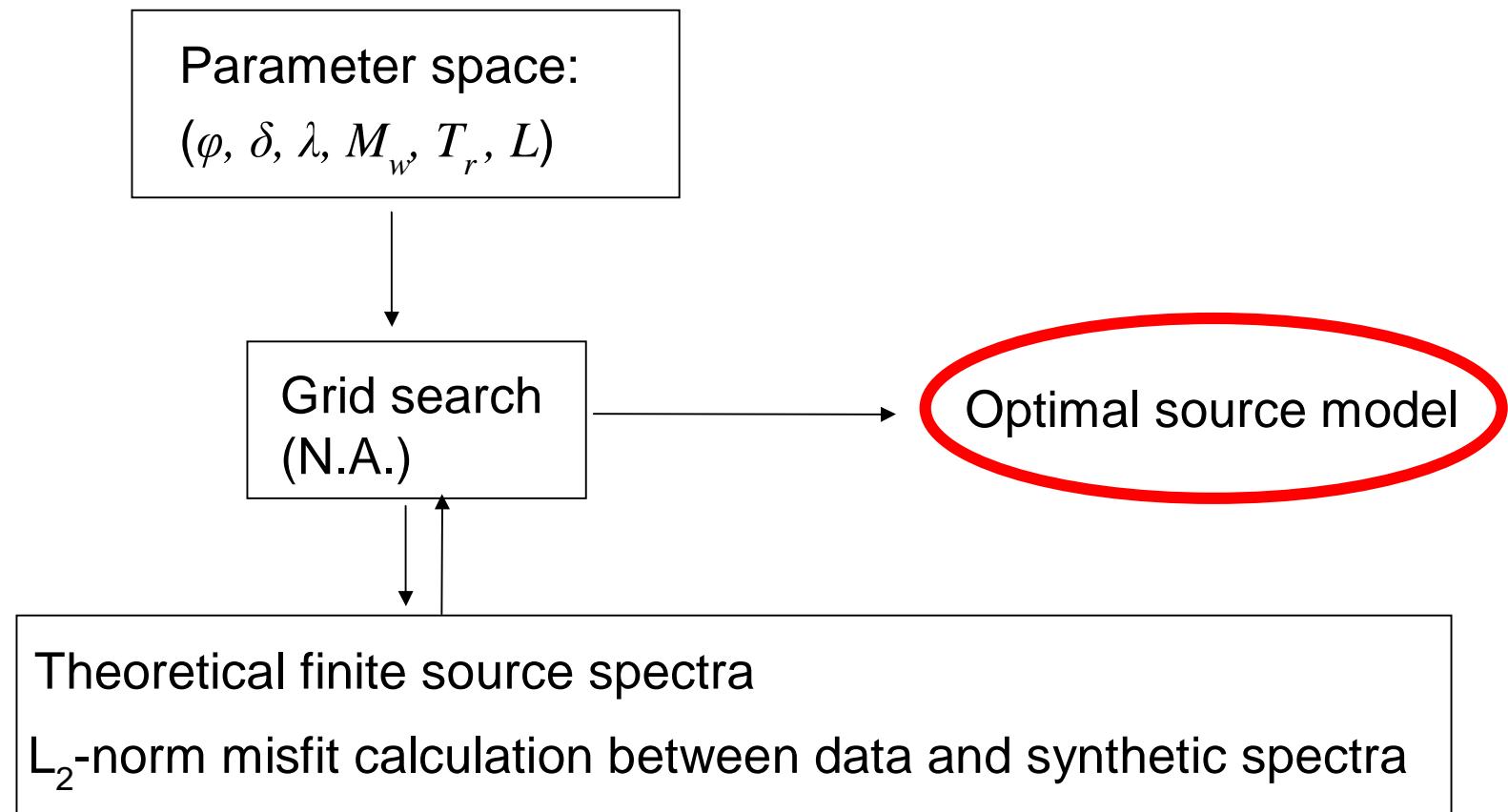
2. Normal mode source model inversion

Probabilistic normal mode source inversion

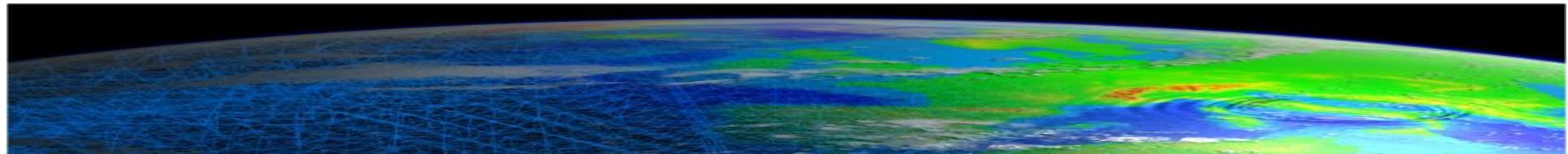
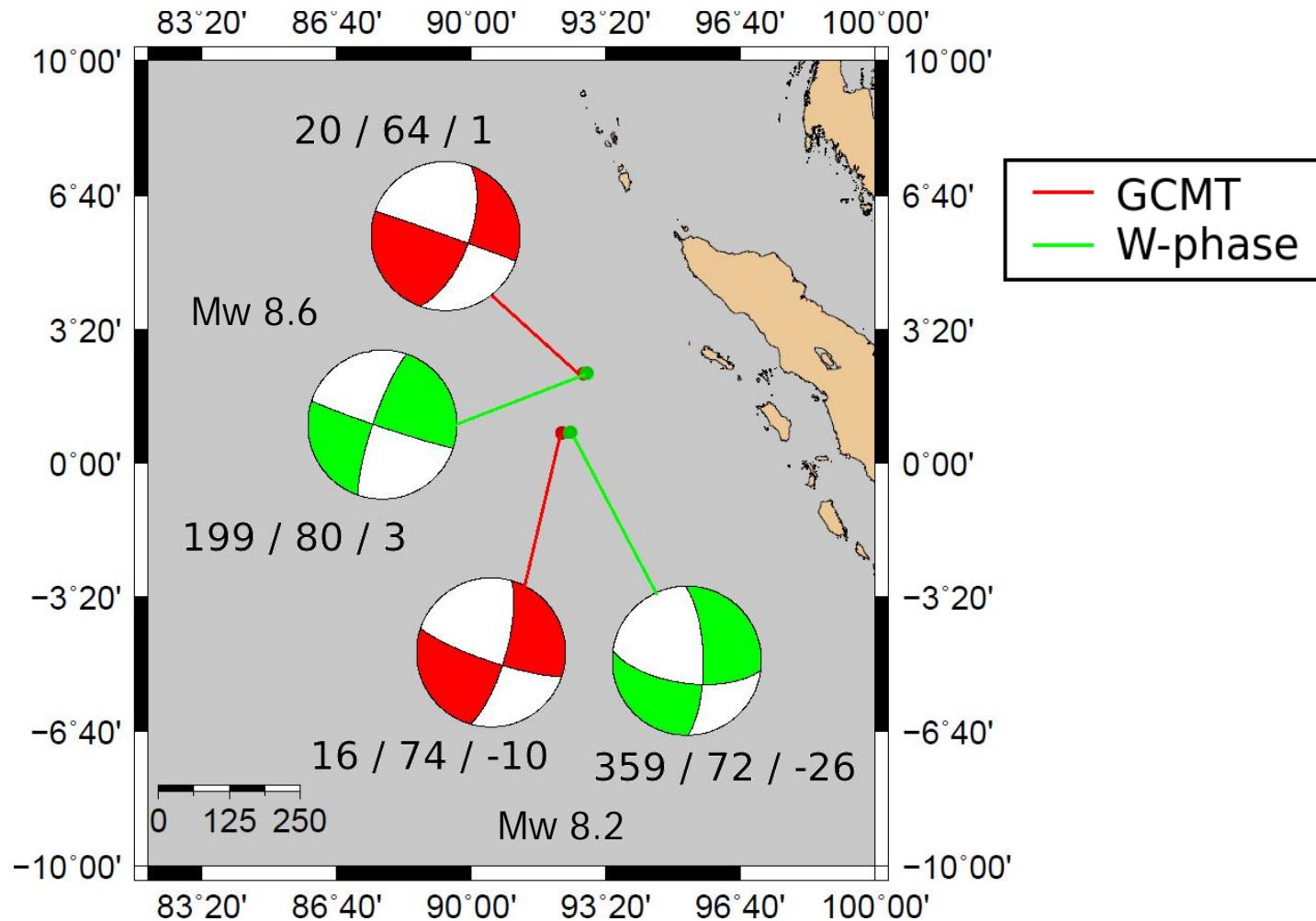


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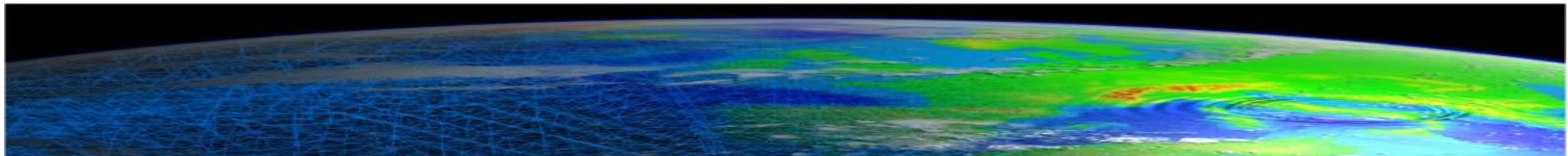
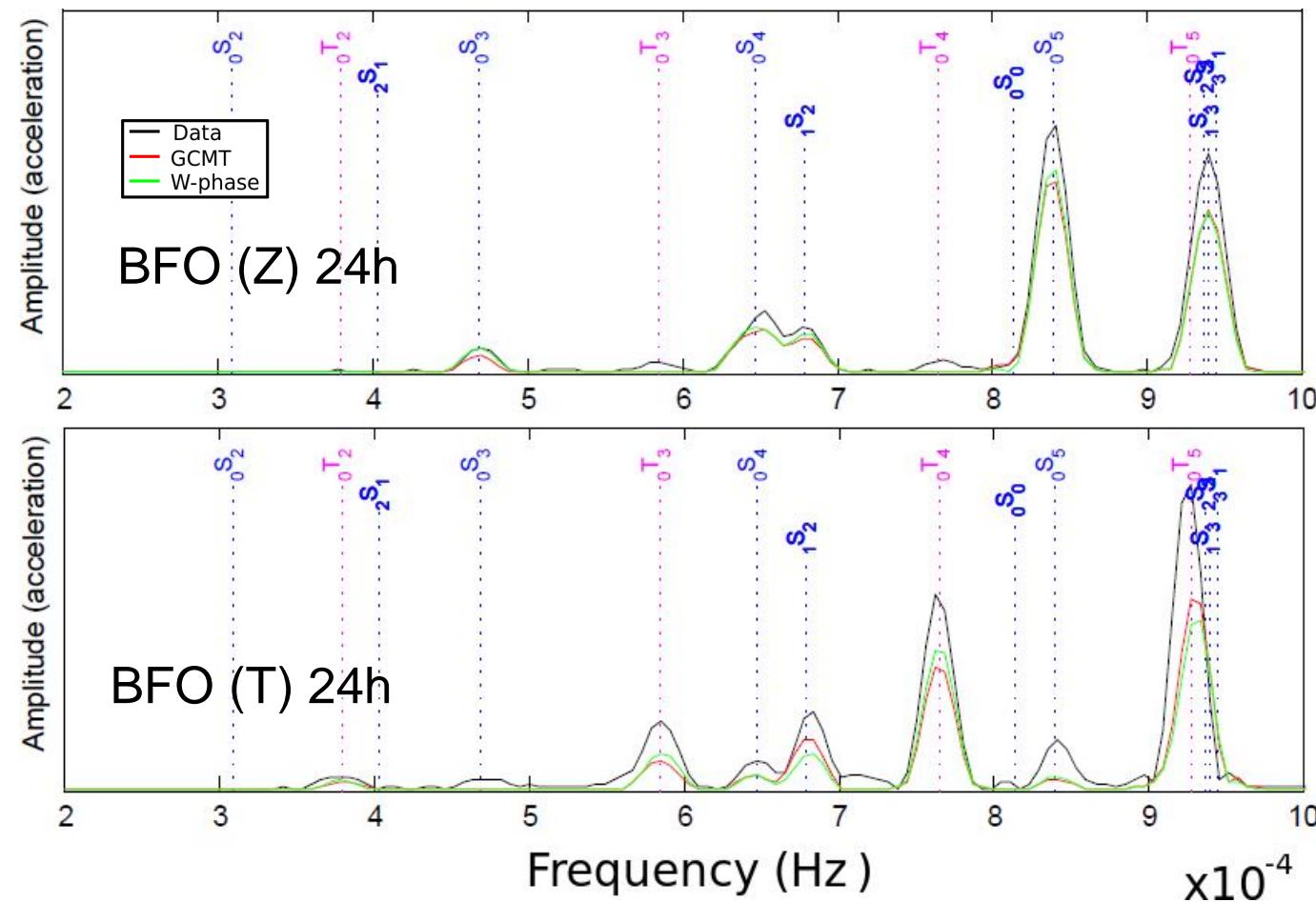
Probabilistic normal mode source inversion



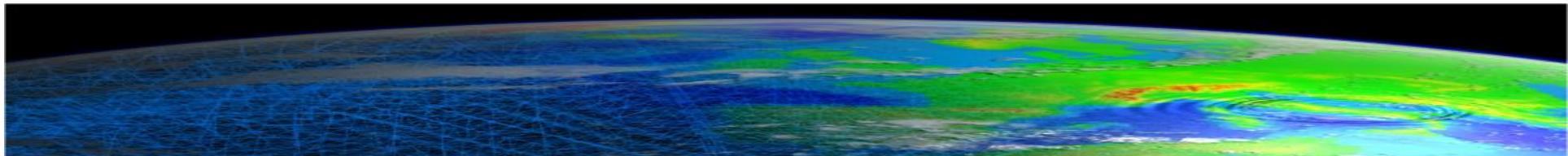
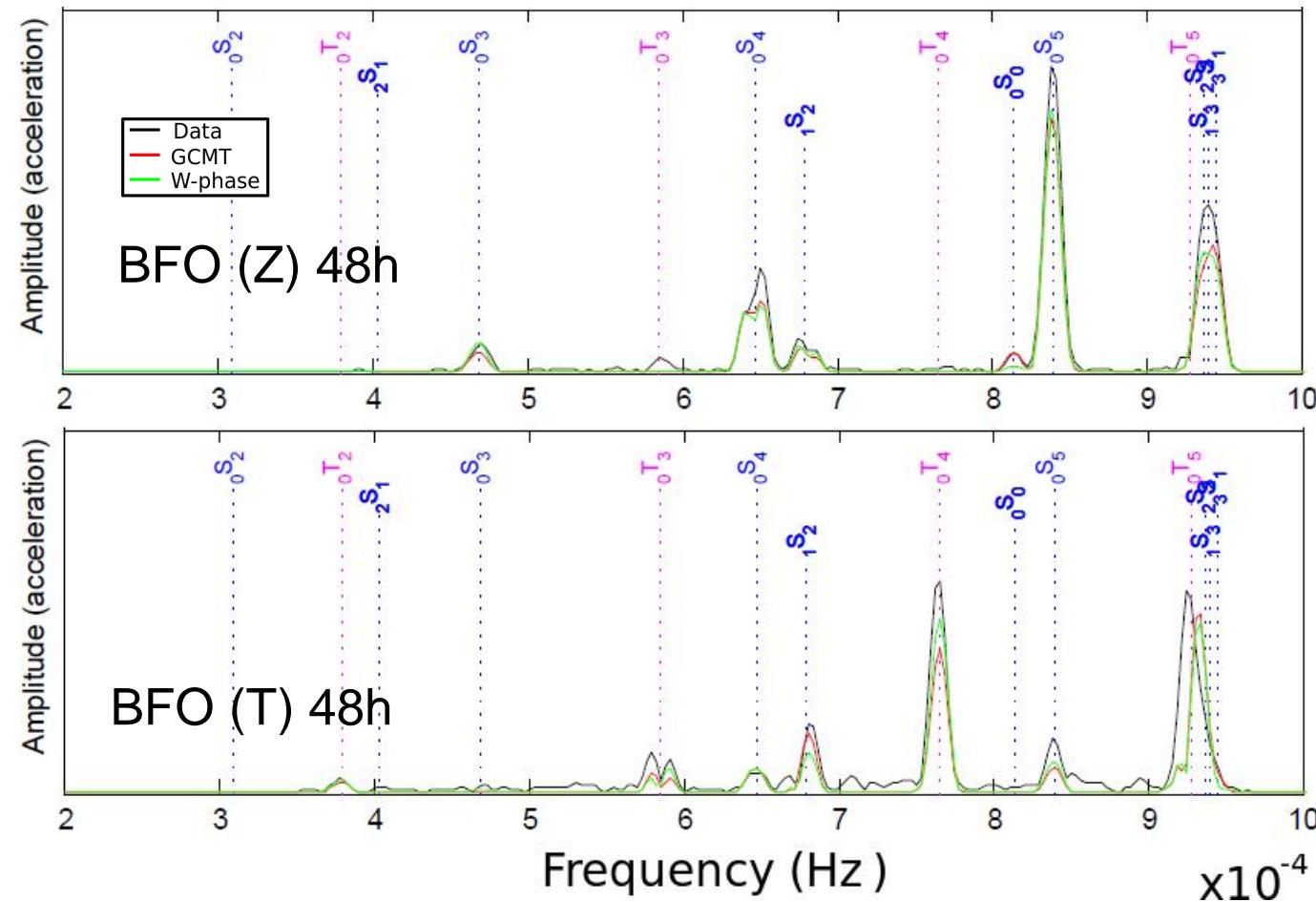
M_w 8.6 & 8.2 Sumatra 2012 earthquakes



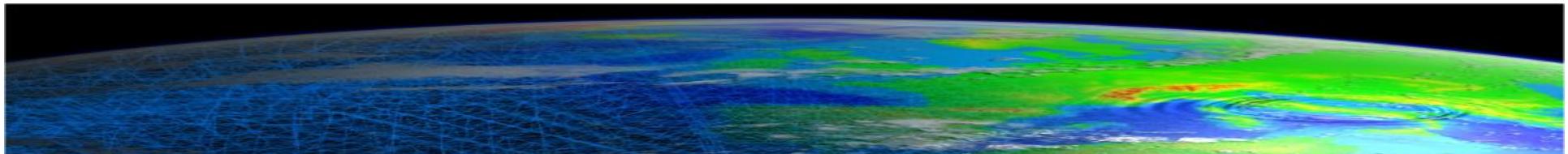
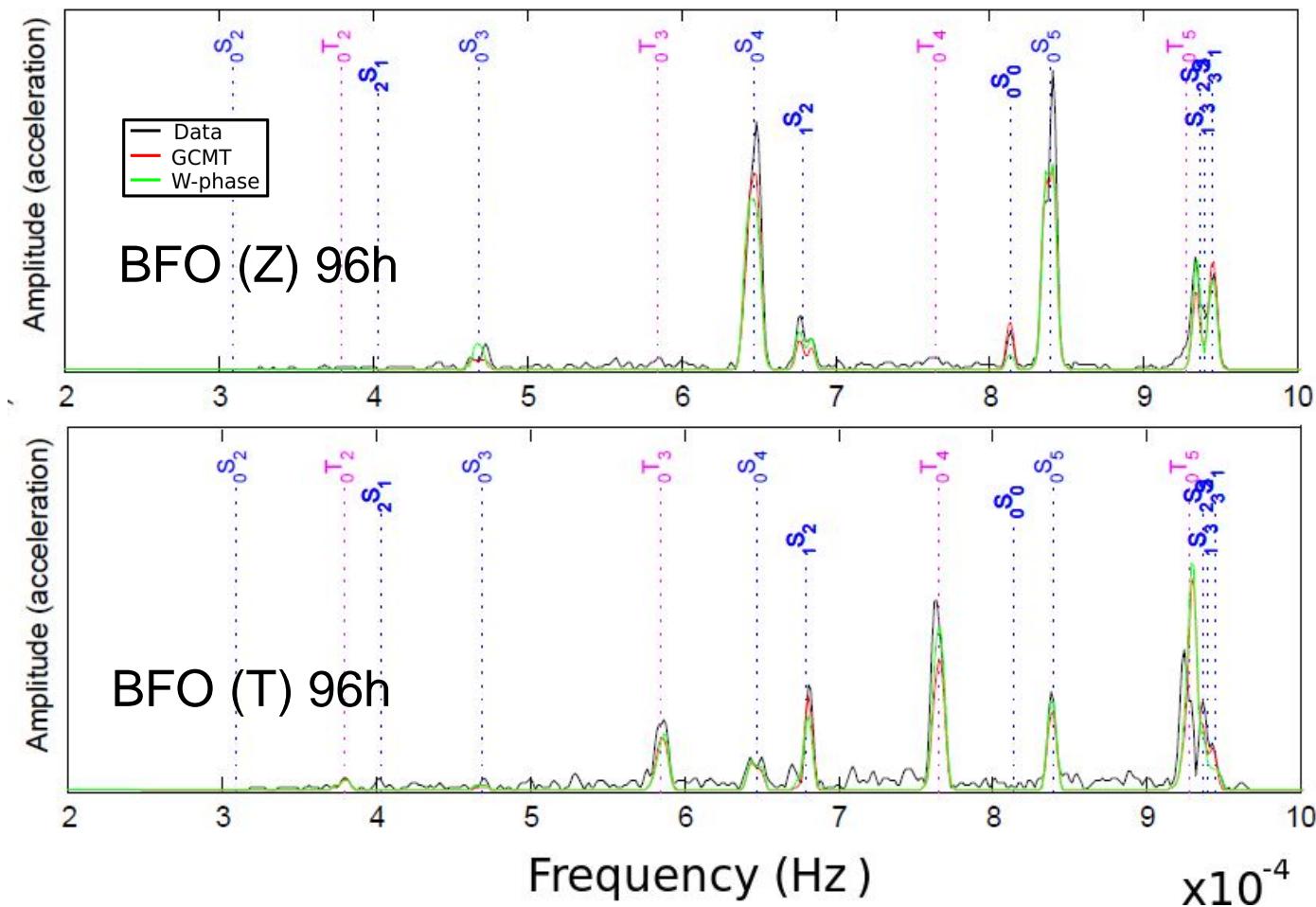
Sumatra 2012 normal mode spectra



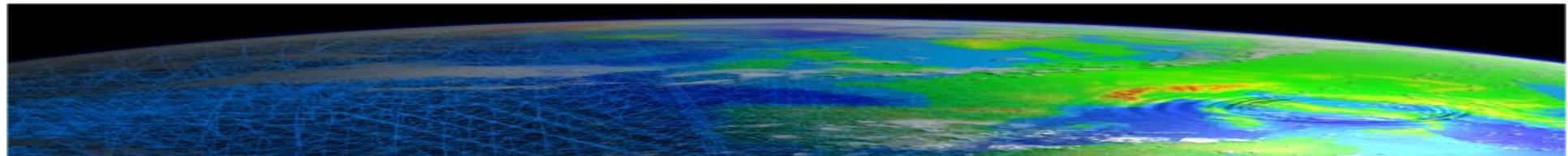
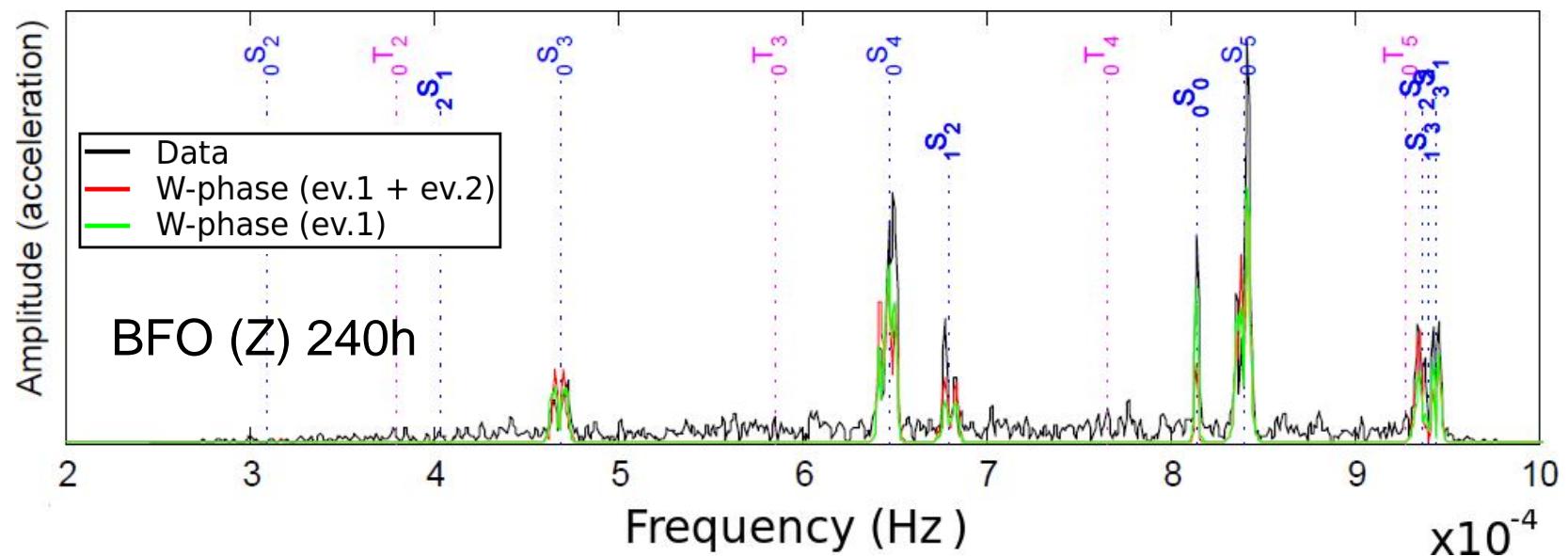
Sumatra 2012 normal mode spectra



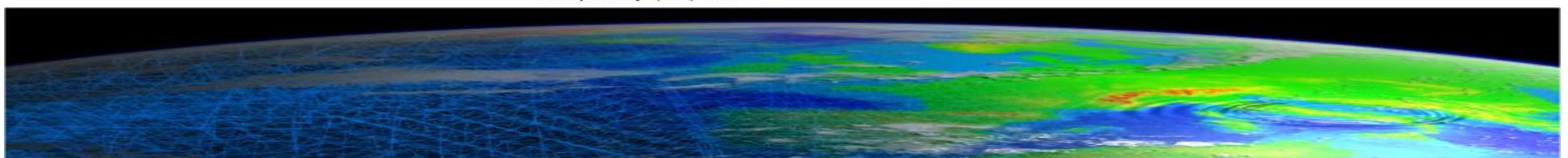
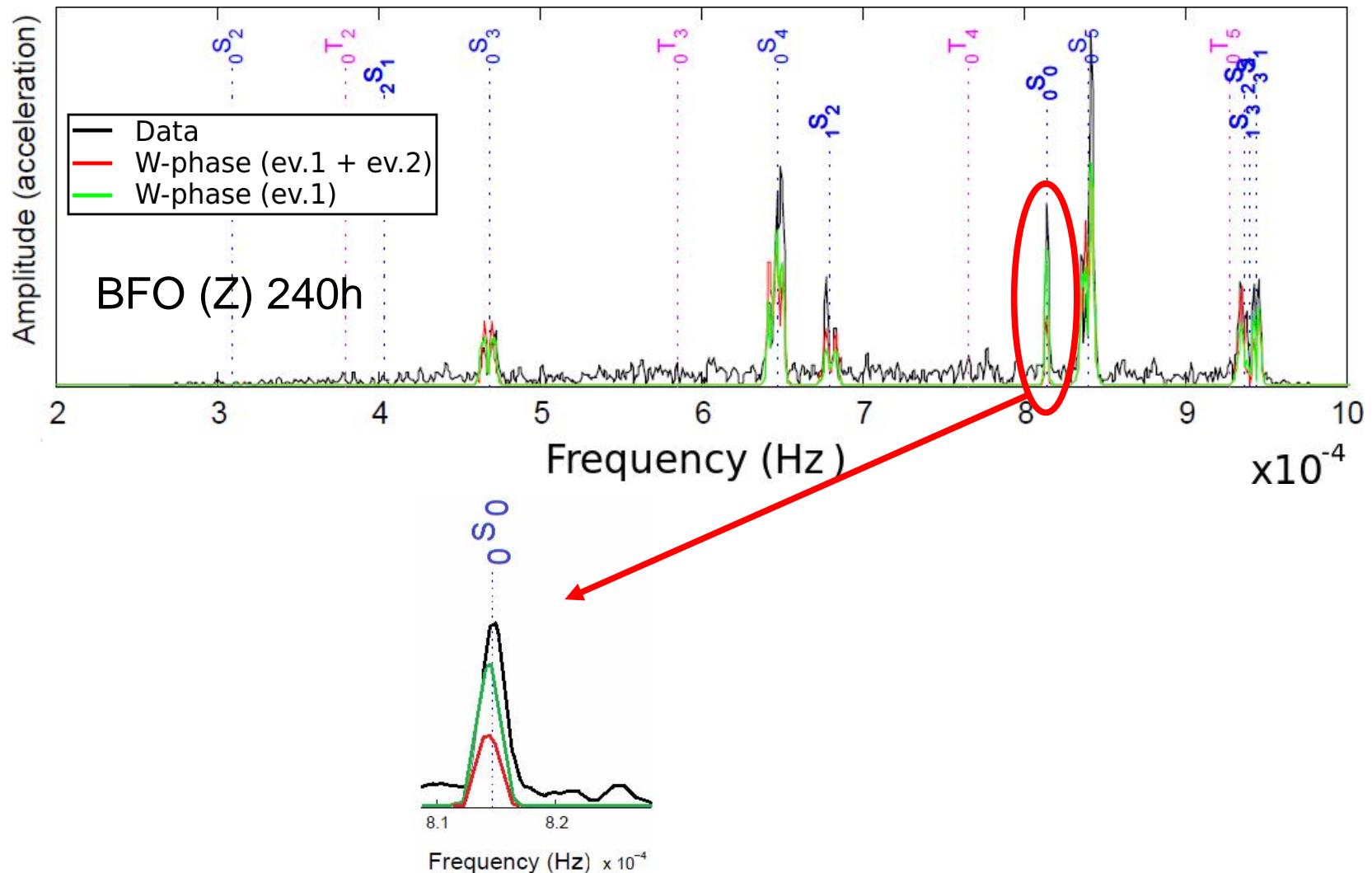
Sumatra 2012 normal mode spectra



Sumatra 2012 normal mode spectra

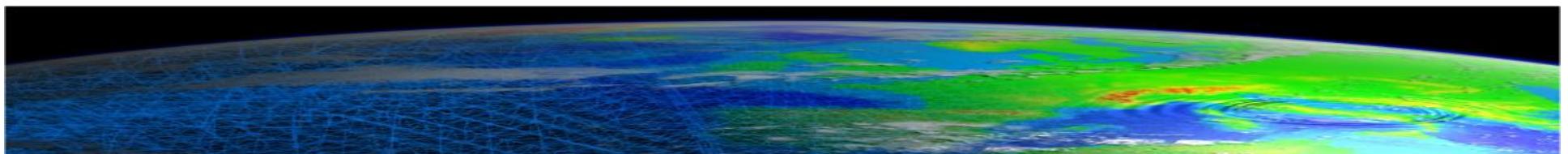


Sumatra 2012 normal mode spectra



Conclusions

- The SCARDEC source parameters explain equally well the normal mode data compared to GCMT.
- Body-wave tests combined with source parameters published in the literature, suggest that the SCARDEC method determines the fault dip angle slightly better than GCMT.
- We developed a linear inversion code which determines the singlets' initial phases of split multiplets and from these measurements, the rupture time and length can be retrieved.
- Rupture length inversions are affected by the fault's strike and the location (epicentre, depth).
- 3D structure affects strongly both the rupture time and length.



$$\alpha_{fs}^m(x,\omega) = \alpha_{ps}^m(x,\omega) \cdot F_m$$

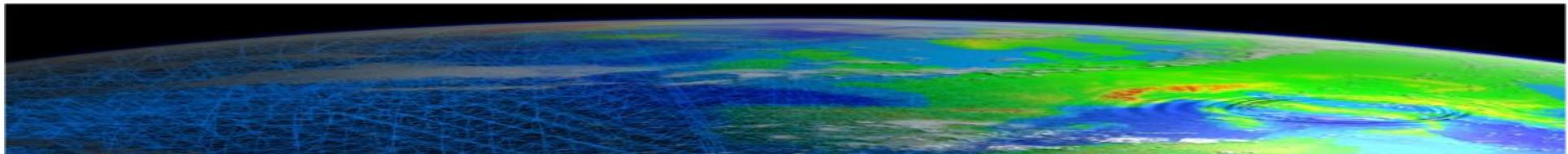
$$F_m = \frac{\sin(X_m)}{X_m} e^{-iX_m}$$

$$\begin{bmatrix} d_{a_1}^j \\ d_{b_1}^j \\ d_{a_2}^j \\ d_{b_2}^j \\ . \\ . \\ d_{a_n}^j \\ d_{b_n}^j \end{bmatrix} = \begin{bmatrix} G_{a_1}^j & -G_{b_1}^j \\ G_{b_1}^j & G_{a_1}^j \\ G_{a_2}^j & -G_{b_2}^j \\ G_{b_2}^j & G_{a_2}^j \\ . & . \\ . & . \\ G_{a_n}^j & -G_{b_n}^j \\ G_{b_n}^j & G_{a_n}^j \end{bmatrix} \times \begin{bmatrix} Re(F_m) \\ Im(F_m) \end{bmatrix}$$

$$X_m = \frac{\pi T_r}{T_m} + \frac{L m \sin(\phi)}{2 r_o \sin(\theta)}$$

$$\begin{bmatrix} X_{m_1} \\ X_{m_2} \\ . \\ . \\ X_{m_n} \end{bmatrix} = \begin{bmatrix} \frac{\pi}{T_{m_1}} & \frac{L m_1 \sin(\phi)}{2 r_o \sin(\theta)} \\ \frac{\pi}{T_{m_2}} & \frac{L m_2 \sin(\phi)}{2 r_o \sin(\theta)} \\ . & . \\ . & . \\ \frac{\pi}{T_{m_n}} & \frac{L m_n \sin(\phi)}{2 r_o \sin(\theta)} \end{bmatrix} \times \begin{bmatrix} T_r \\ L \end{bmatrix}$$

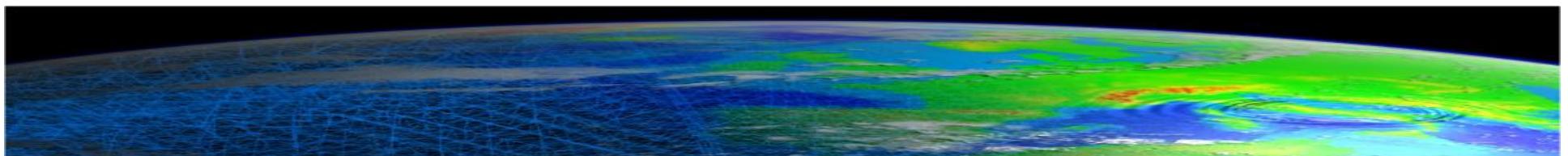
$$F_m = (G^T C_d^{-1} G)^{-1} G^T C_d^{-1} d$$



$$\alpha_{fs}^m(x, \omega) = \sum_{i=1}^6 (\psi_i^m(x, \omega) \cdot M_i) \cdot F_m$$

$$\begin{bmatrix} \alpha_1^{ps} \\ \alpha_2^{ps} \\ \vdots \\ \alpha_n^{ps} \end{bmatrix} = \begin{bmatrix} \psi_1^{(M_1=1)} & \psi_1^{(M_2=1)} & \psi_1^{(M_3=1)} & \psi_1^{(M_4=1)} & \psi_1^{(M_5=1)} & \psi_1^{(M_6=1)} \\ \psi_2^{(M_1=1)} & \psi_2^{(M_2=1)} & \psi_2^{(M_3=1)} & \psi_2^{(M_4=1)} & \psi_2^{(M_5=1)} & \psi_2^{(M_6=1)} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \psi_n^{(M_1=1)} & \psi_n^{(M_2=1)} & \psi_1^{(M_3=1)} & \psi_n^{(M_4=1)} & \psi_n^{(M_5=1)} & \psi_n^{(M_6=1)} \end{bmatrix} \times \begin{bmatrix} M_1 \\ M_2 \\ M_3 \\ M_4 \\ M_5 \\ M_6 \end{bmatrix}$$

$$\begin{bmatrix} \alpha_1^{ps} \\ \alpha_2^{ps} \\ \vdots \\ \alpha_n^{ps} \end{bmatrix} = \begin{bmatrix} \frac{\partial a_1^{ps}}{\partial M_1} & \frac{\partial a_1^{ps}}{\partial M_2} & \frac{\partial a_1^{ps}}{\partial M_3} & \frac{\partial a_1^{ps}}{\partial M_4} & \frac{\partial a_1^{ps}}{\partial M_5} & \frac{\partial a_1^{ps}}{\partial M_6} \\ \frac{\partial a_2^{ps}}{\partial M_1} & \frac{\partial a_2^{ps}}{\partial M_2} & \frac{\partial a_2^{ps}}{\partial M_3} & \frac{\partial a_2^{ps}}{\partial M_4} & \frac{\partial a_2^{ps}}{\partial M_5} & \frac{\partial a_2^{ps}}{\partial M_6} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \frac{\partial a_n^{ps}}{\partial M_1} & \frac{\partial a_n^{ps}}{\partial M_2} & \frac{\partial a_n^{ps}}{\partial M_3} & \frac{\partial a_n^{ps}}{\partial M_4} & \frac{\partial a_n^{ps}}{\partial M_5} & \frac{\partial a_n^{ps}}{\partial M_6} \end{bmatrix} \times \begin{bmatrix} M_1 \\ M_2 \\ M_3 \\ M_4 \\ M_5 \\ M_6 \end{bmatrix}$$



Synthetic test

Parameter space:

<i>Strike</i>	0.0	359.0
M_w	7.8	9.5
T_r	30.0	600.0
L	60.0	1440.0

Best fit model:

<i>Strike</i>	340.7°
<i>Dip</i>	6.1°
<i>Rake</i>	107.0°
M_w	9.3
T_r	555.5 s
L	1119.4 km

Input model:

<i>Strike</i>	343.0°
<i>Dip</i>	6.1°
<i>Rake</i>	107.0°
M_w	9.3
T_r	552.4 s
L	1153.9 km

