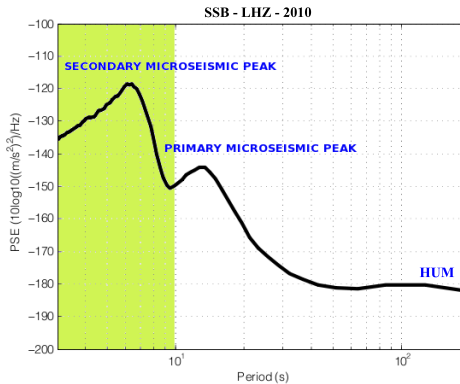




# 1-Modelling secondary microseismic noise

## 2-Modelling body waves sources

### 3-Modelling long period noise



# Noise sources discretisation and synthetic seismogram

Theory by

*Longuet-Higgins, 1950*

and *Hasselmann, 1963*:

Seismic noise sources:

**single vertical forces**

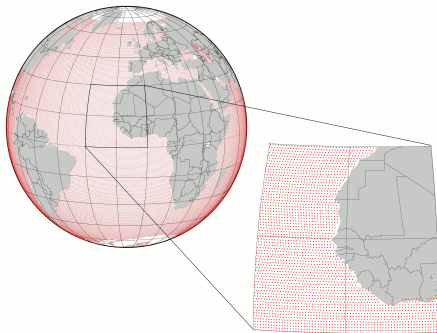
**close by the ocean**

**surface**

# Noise sources discretisation and synthetic seismogram

Theory by  
*Longuet-Higgins, 1950*  
and *Hasselmann, 1963*:

Seismic noise sources:  
**single vertical forces**  
**close by the ocean**  
**surface**



**Synthetic seismogram by using a single vertical force:**

$$\mathbf{u}(\mathbf{r}, \theta, \phi) = \gamma_l^2 F_r v_r \mathbf{U}_k(\mathbf{r}_s) \mathbf{U}_k(\mathbf{r}_r) Y_k^0(\Theta_s, \Phi_s) Y_k^0(\Theta_r, \Phi_r) \exp(i\omega_k t)$$

# Modelling noise sources as vertical forces

## Vertical force amplitude

(WAVEWATCH III<sup>R</sup> - Ardhuin et al., 2011):

$$F(f_s, dS, df_s) = 2\pi \sqrt{F_p(K \simeq 0, f_s)} \times dS \times df_s$$

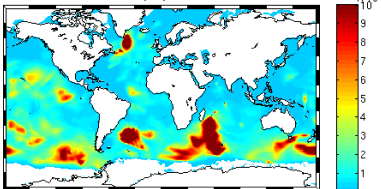
where

$$F_p(K \simeq 0, f_s) = \rho_w^2 g^2 f_s E^2(f)$$

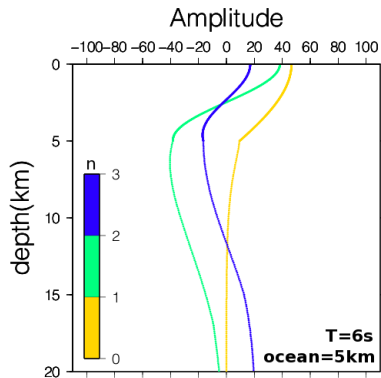
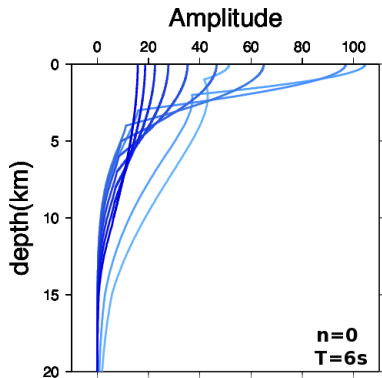
is the equivalent wave-induced pressure spectrum at ocean surface.

$E(f)$  is the surface elevation variance of the two ocean trains.

Vertical force (N) at T=5.685 sec



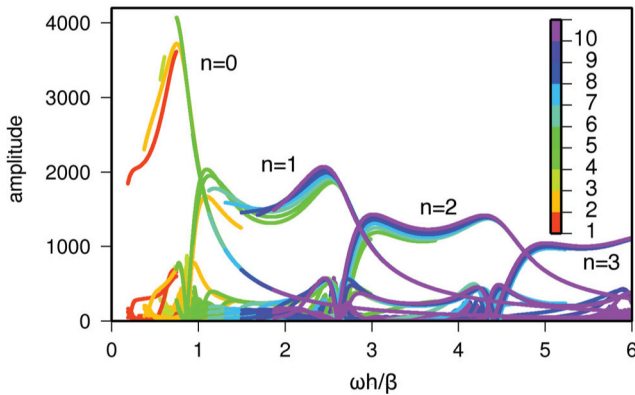
Eigenfunctions  ${}_0U_I$ ,  ${}_1U_I$ ,  ${}_2U_I$  respectively at 6s:



by using normal modes in PREM model:

$$c_n = \frac{{}_nU_l(\mathbf{r}_r) {}_nU_l(\mathbf{r}_s)}{{}_n\omega_l}$$

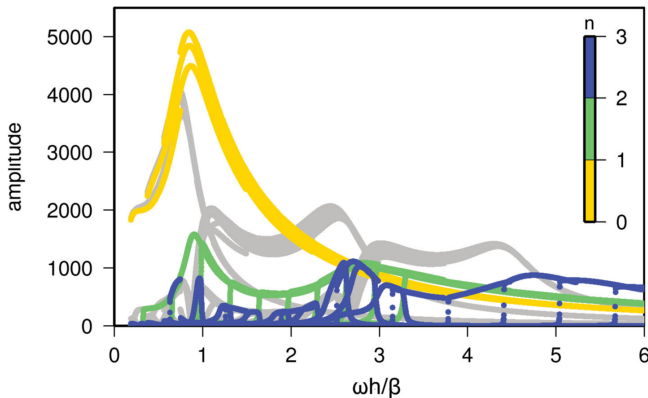
${}_nU_l(\mathbf{r}_r), {}_nU_l(\mathbf{r}_s)$  = eigenfunctions at receiver and source position;  
 ${}_n\omega_l$  = eigenfrequency



and considering the receiver on land:

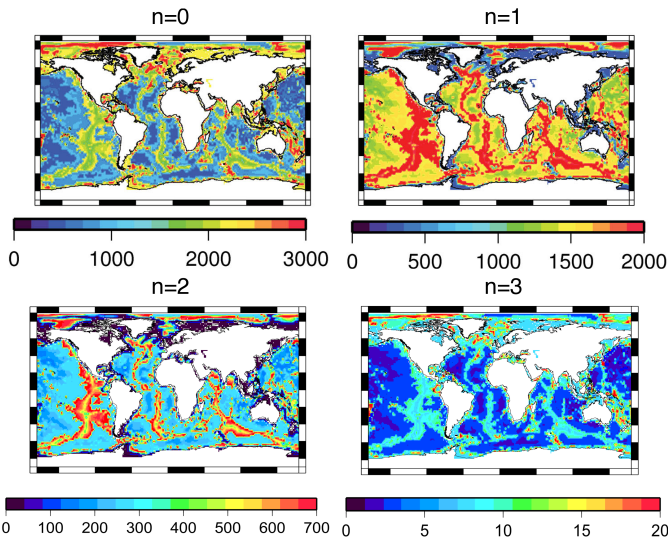
$$c_n = \frac{{}_nU_l(\mathbf{r}_r) {}_nU_l(\mathbf{r}_s)}{{}_n\omega_l}$$

${}_nU_l(\mathbf{r}_r), {}_nU_l(\mathbf{r}_s)$  = eigenfunctions at receiver and source position;  
 ${}_n\omega_l$  = eigenfrequency



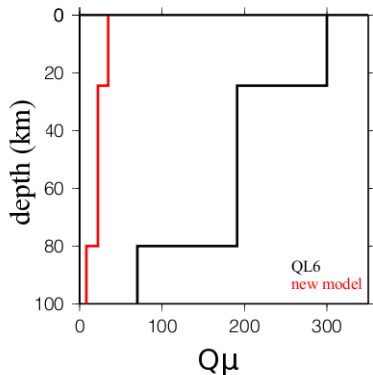


# Maps of amplification factor - $n=0,1,2,3$ - $T=6$ s



# Apparent attenuation model

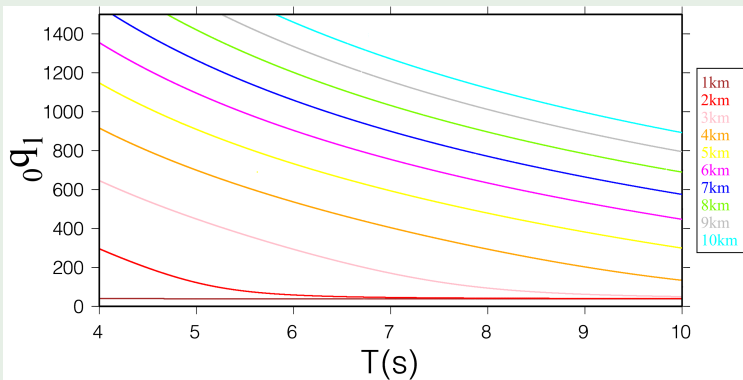
**depth = 0 – 100 km:**  
 decreasing of all values of  
 QL6  
 ↓  
**depth  $\geq$  100 km:**  
 QL6  
 (*Durek and Ekström, 1996*)



# Attenuation of Rayleigh fundamental mode ( $n=0$ )

The attenuation of Rayleigh waves:

- decreases with increasing period;
- increases with increasing water depth.



Modelling secondary microseisms

oooooooo●oooo

Modelling body wave source

oooo

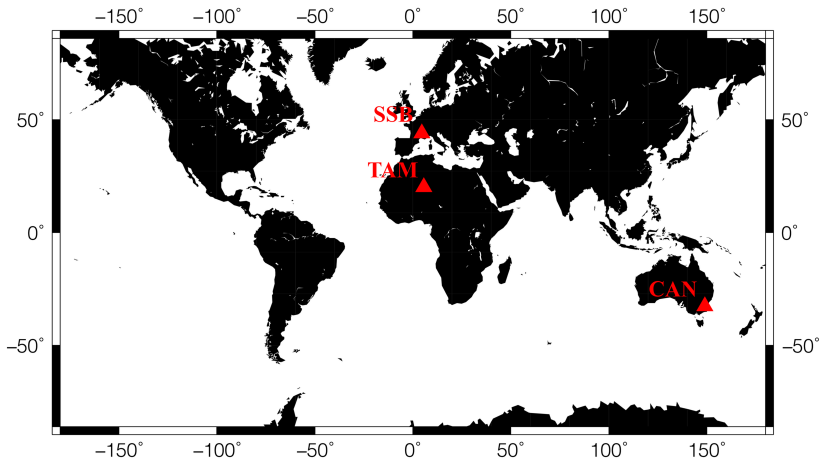
Modelling long period noise

ooo

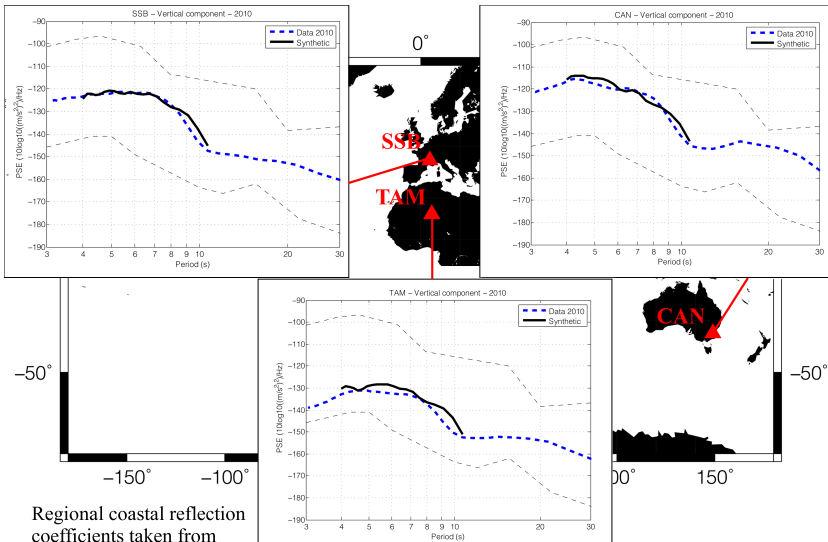
Conclusions and perspectives

o

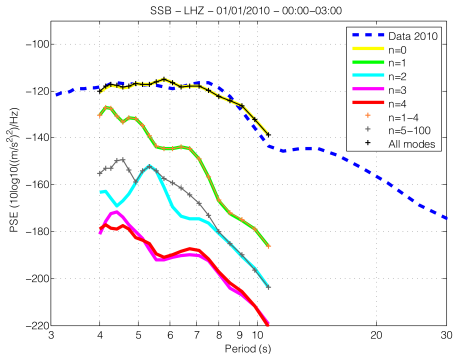
Vertical components of noise spectra: Rayleigh waves modelling



## Vertical components of noise spectra: Rayleigh waves modelling

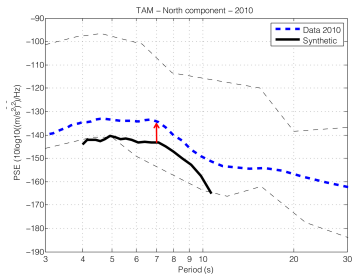
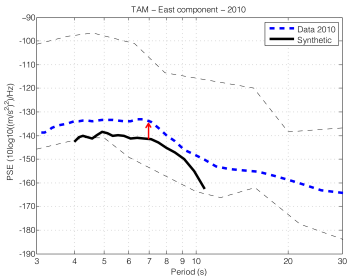


Regional coastal reflection coefficients taken from Stutzmann et al., 2012



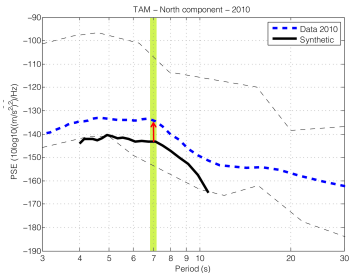
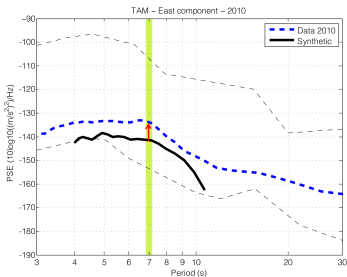
- The amplitude decreases with increasing the overtone number;
- The differences between them become smaller with increasing the overtone number;
- The amplitude computed with the fundamental mode is comparable with the amplitude computed with 100 modes.

## Love wave energy estimation in horizontal components



Synthetic spectra: only Rayleigh waves

## Love wave energy estimation in horizontal components



Missing Love wave energy estimation: e.g. 7 s

Power Spectral Energy (Raileigh & Love waves)  $\simeq -135$  dB

It is necessary:  $\frac{E_{Love}}{E_{Rayleigh}} \sim 0.65$

→ compatible with *Nishida et al.*, 2008.

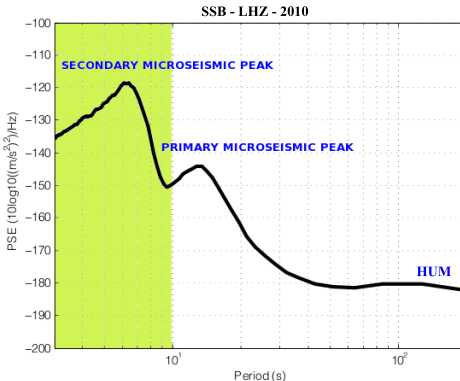


# 1-Modelling secondary microseismic noise

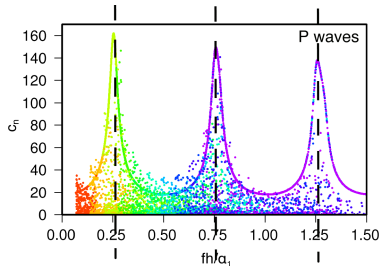
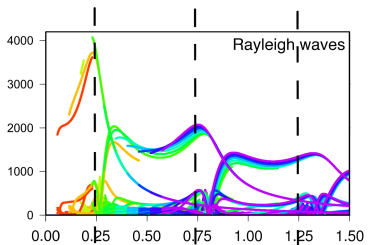
## 2-Modelling body waves sources:

work in progress!

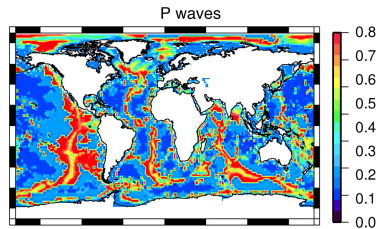
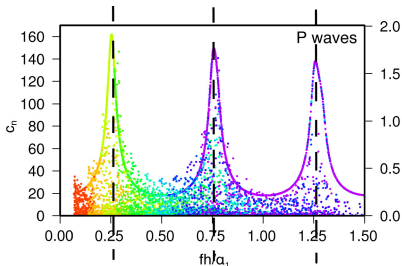
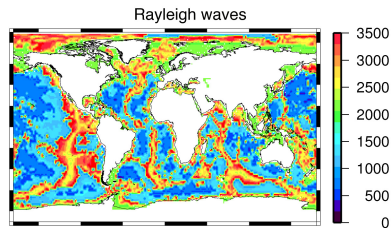
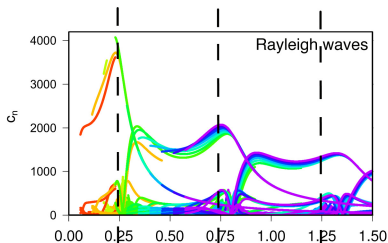
## 3-Modelling long period noise



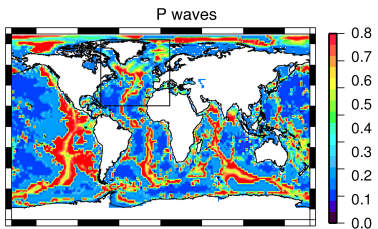
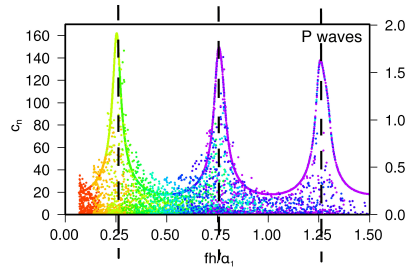
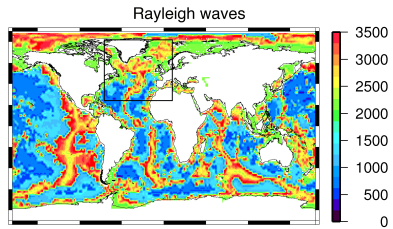
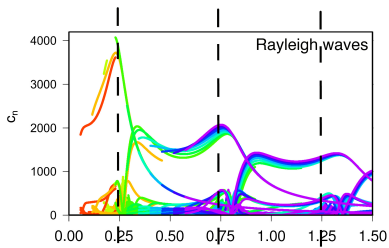
# Modelling body wave sources: amplification factor



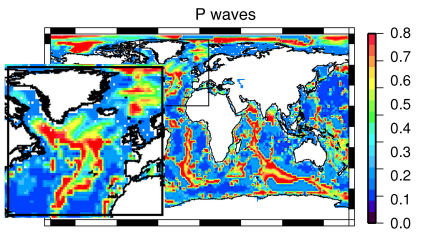
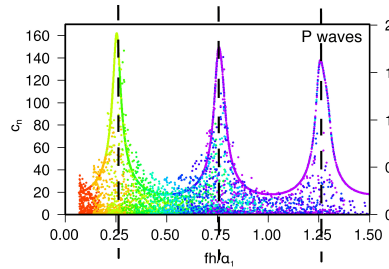
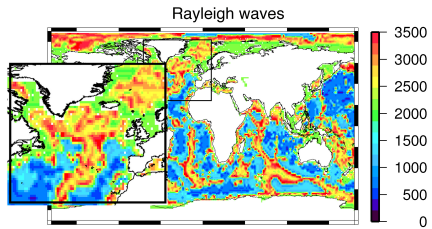
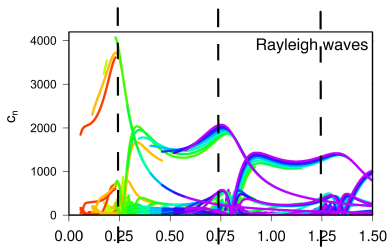
# Modelling body wave sources: amplification factor $T=7s$



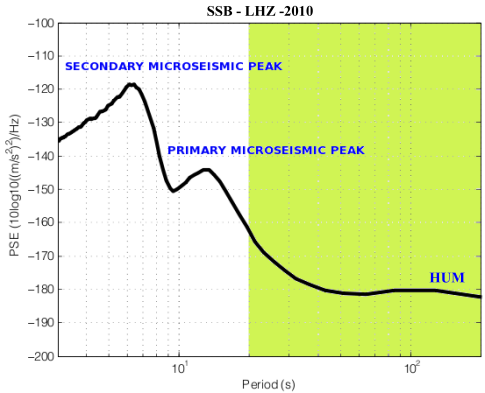
# Modelling body wave sources: amplification factor $T=7s$



# Modelling body wave sources: amplification factor $T=7s$



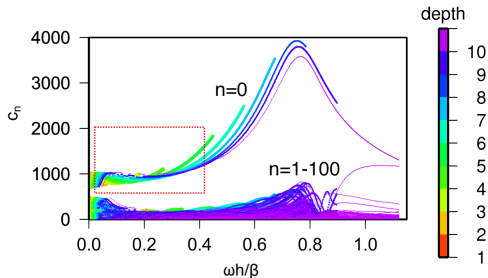
- 1-Modelling secondary microseismic noise
- 2-Modelling body waves sources
- 3-Modelling long period noise: **work in progress!**



Long period noise:  $T=20-500$  s

$$c_n = \frac{{}_nU_l(\mathbf{r}_r){}_nU_l(\mathbf{r}_s)}{{}_n\omega_l}$$

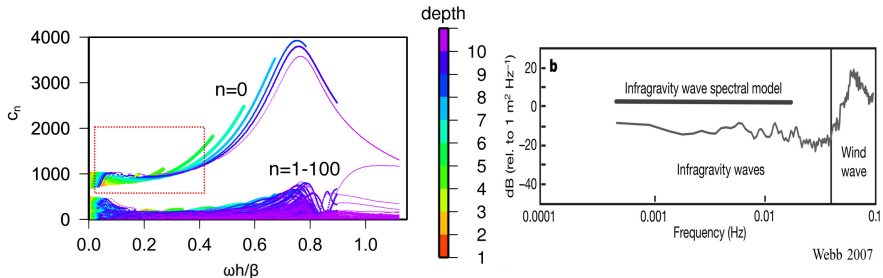
${}_nU_l(\mathbf{r}_r), {}_nU_l(\mathbf{r}_s)$  = eigenfunctions at receiver and source position;  
 ${}_n\omega_l$  = eigenfrequency



Long period noise:  $T=20-500$  s

$$c_n = \frac{{}_nU_l(\mathbf{r}_r) {}_nU_l(\mathbf{r}_s)}{{}_n\omega_l}$$

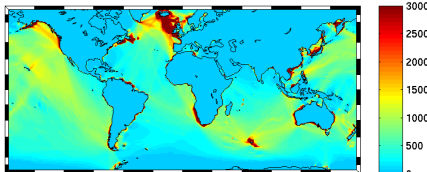
${}_nU_l(\mathbf{r}_r), {}_nU_l(\mathbf{r}_s)$  = eigenfunctions at receiver and source position;  
 ${}_n\omega_l$  = eigenfrequency



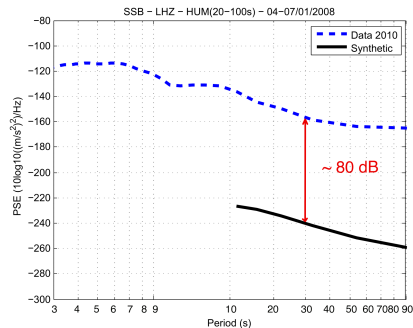
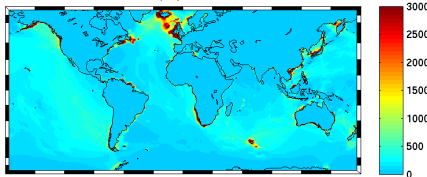


# Modelling long period ( $T=20-100$ s) vertical spectra by considering interaction of infragravity waves

Vertical force (N) at  $T=50.9048$  sec



Vertical force (N) at  $T=90.181$  sec



**First computations: noise levels is too low by  $\sim 80$ dB**

# Conclusions

- We model noise **Rayleigh wave** amplitude considering:
  - sources as vertical single forces;
  - source amplification coefficients in a realistic Earth model;
  - an empirical attenuation model.
- We estimate missing **Love wave** energy on the horizontal spectra;
- We model seismic noise **body wave** sources;
- We observe that **long period noise** sources are not frequency dependent;
- **TO BE DONE:**  
modelling noise body waves, Love waves and hum.

