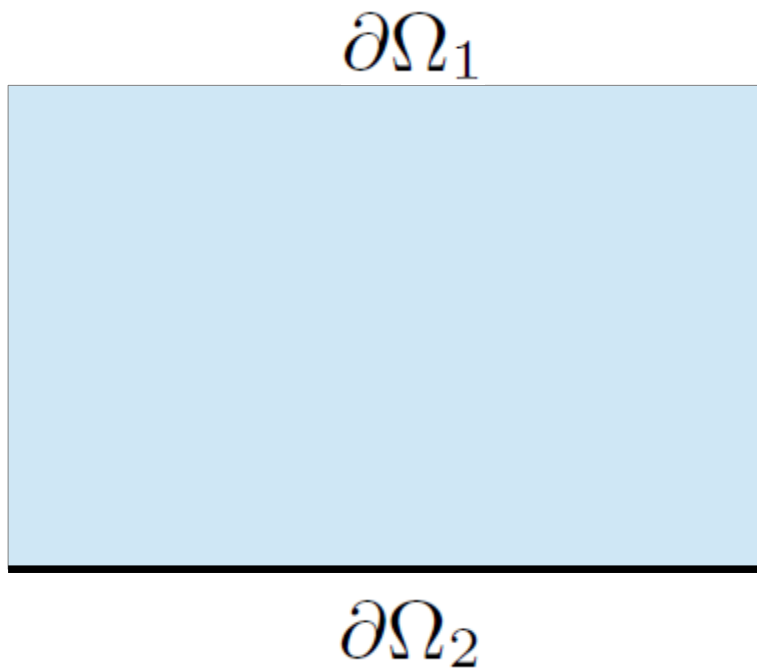


Higher-order adjoint methods and Backus-Gilbert Theory

David Al-Attar, University of Cambridge

A toy inverse problem



$$\rho \partial_t^2 u - \nabla \cdot \mathbf{t} = 0, \quad \mathbf{x} \in \Omega$$

$$\mathbf{t} = \mu \nabla u$$

$$\hat{\mathbf{n}} \cdot \mathbf{t} = 0, \quad \mathbf{x} \in \partial\Omega_1$$

$$u = s, \quad \mathbf{x} \in \partial\Omega_2$$

$$u(\mathbf{x}, 0) = \partial_t u(\mathbf{x}, 0)$$

$$A : L^2(\partial\Omega_2 \times [0, T]; \mathbb{R}) \rightarrow L^2(\partial\Omega_1 \times [0, T]; \mathbb{R})$$

$$s \mapsto A(s) = u|_{\partial\Omega_1 \times [0, T]}$$

Optimization formulation

Objective functional:

$$J(u) = \frac{1}{2} \int_0^T \int_{\partial\Omega_1} w(u - u_{\text{obs}})^2 \, dS \, dt$$

Reduced objective functional:

$$\hat{J}(s) = (J \circ A)(s)$$

Best-fitting model:

$$\tilde{s} = \arg \min_s \hat{J}(s)$$

Solution using adjoint methods

First-order necessary optimality condition:

$$D_s \hat{J}(\tilde{s}) = 0$$

Gradient calculated using first-order adjoint method

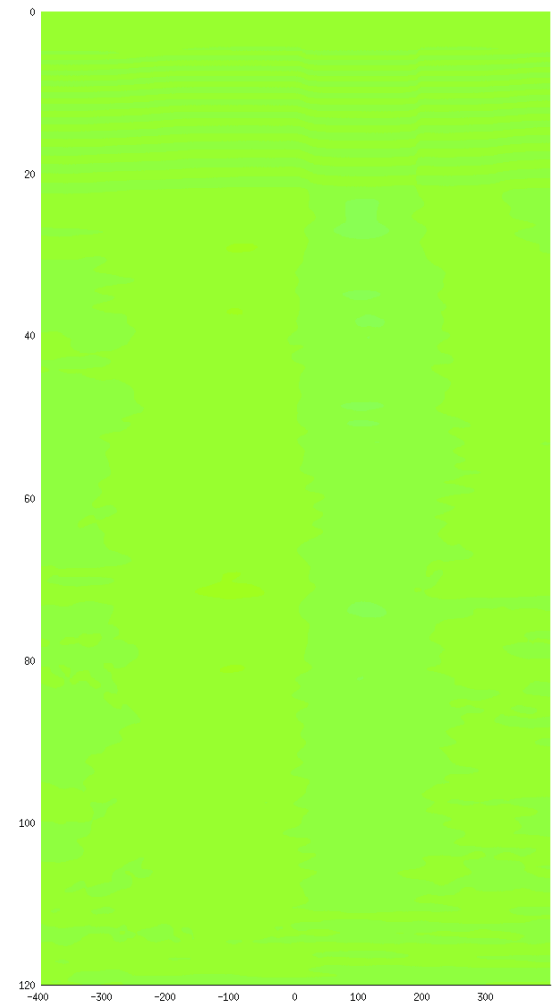
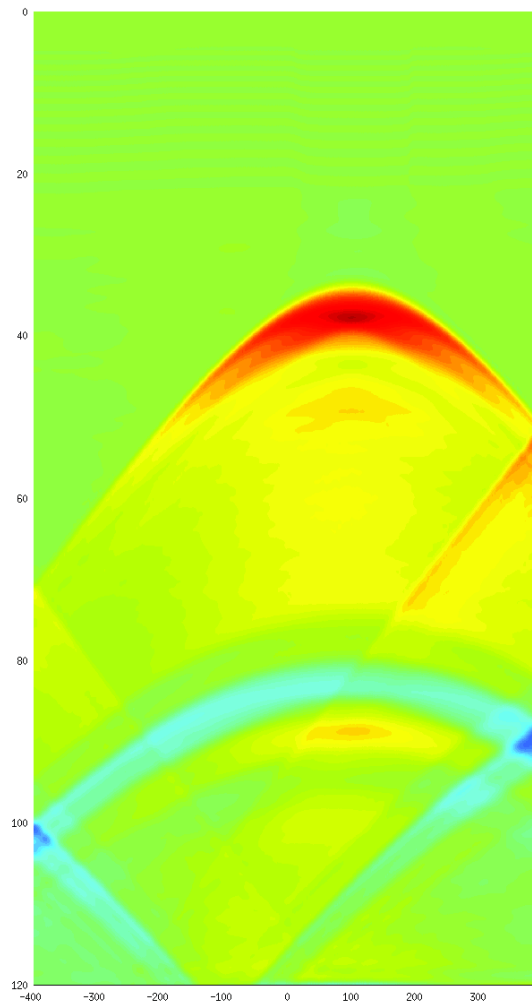
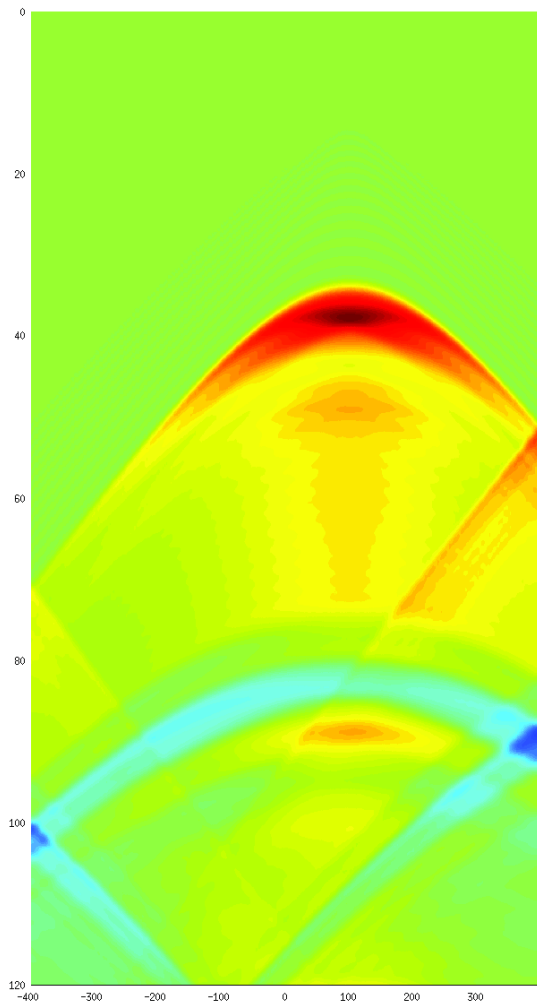
Second-order sufficient optimality condition:

$$D_s^2 \hat{J}(\tilde{s}) > 0$$

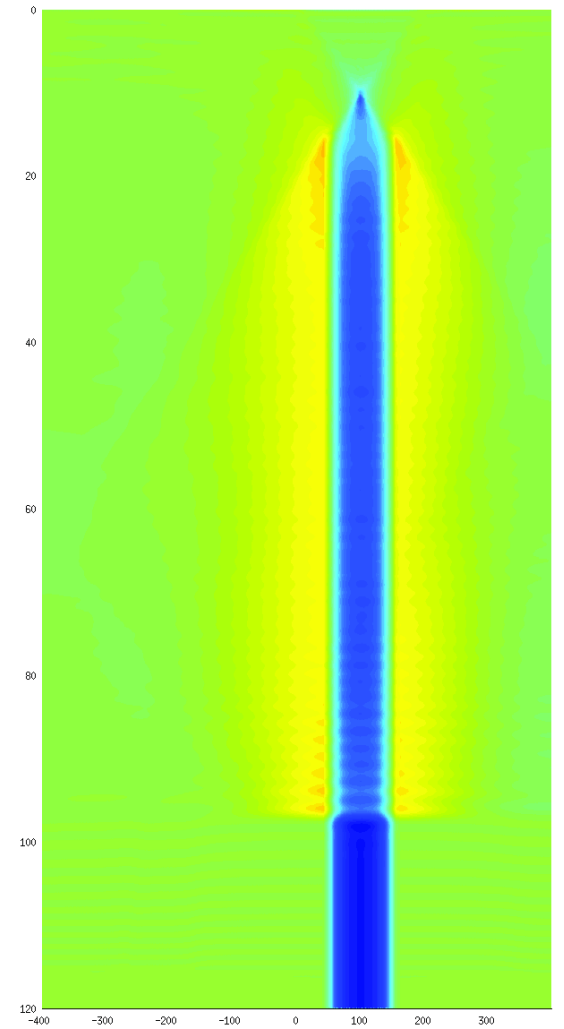
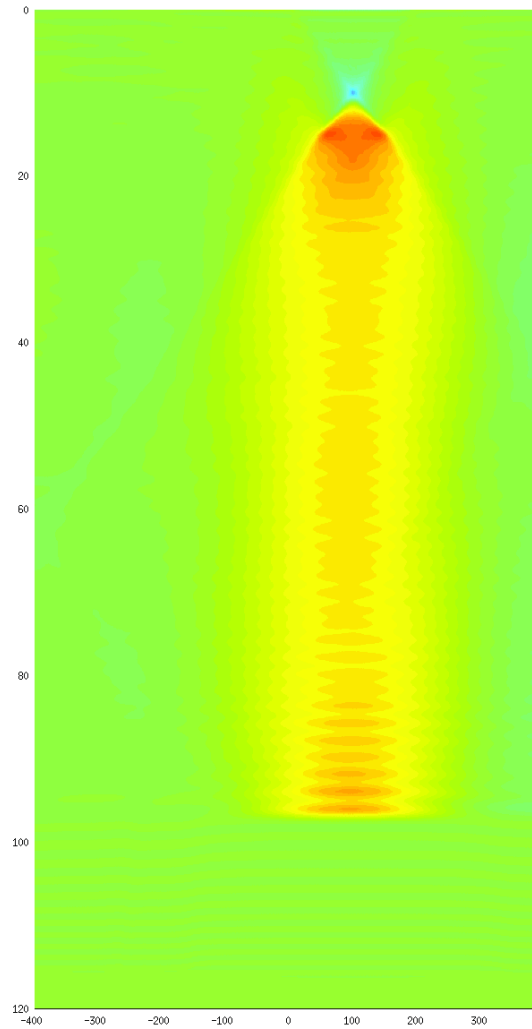
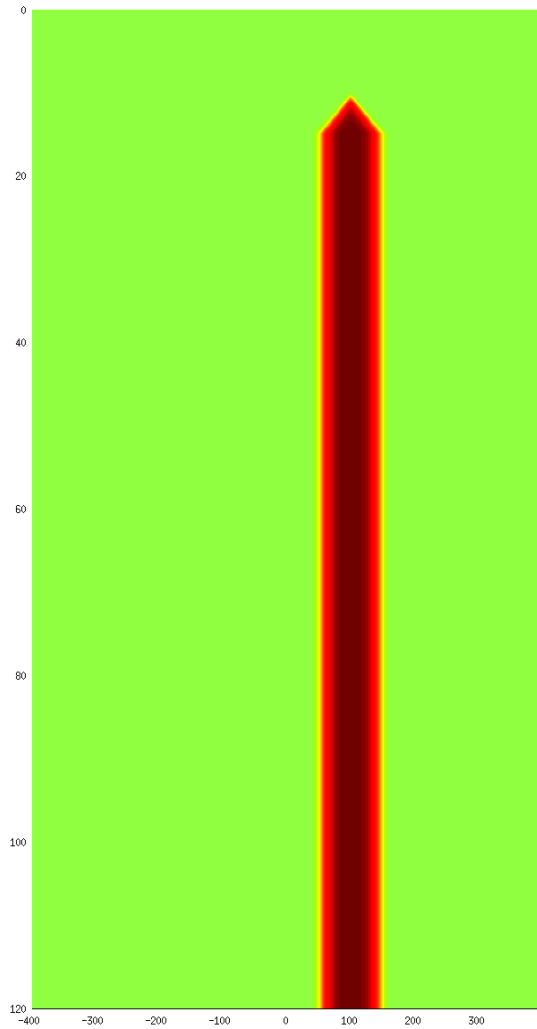
Hessian products calculated using second-order adjoint method

Iterative solution using gradient based methods

Data comparison



Slip comparison



Abstract form of problem

For $A \in L(X; Y)$ we consider:

$$Ax = y \quad J(x) = \frac{1}{2} \|Ax - y\|_Y^2$$

Orthogonal decompositions: $\langle Ax, y \rangle_Y = \langle x, A^*y \rangle_X$

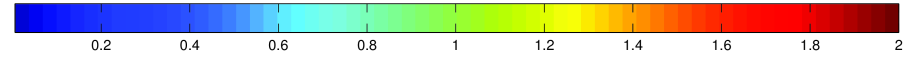
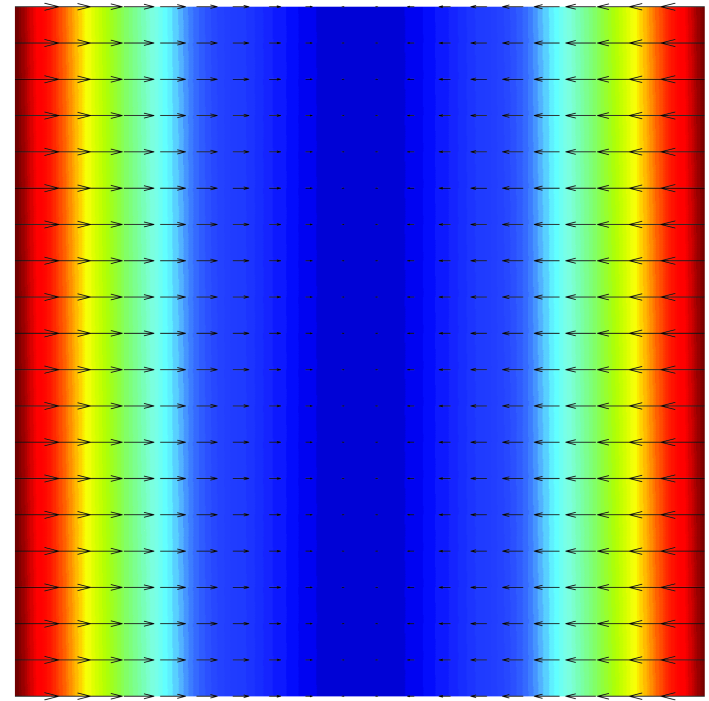
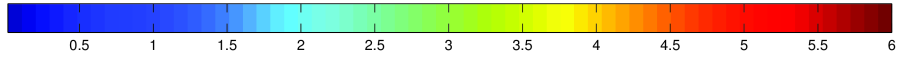
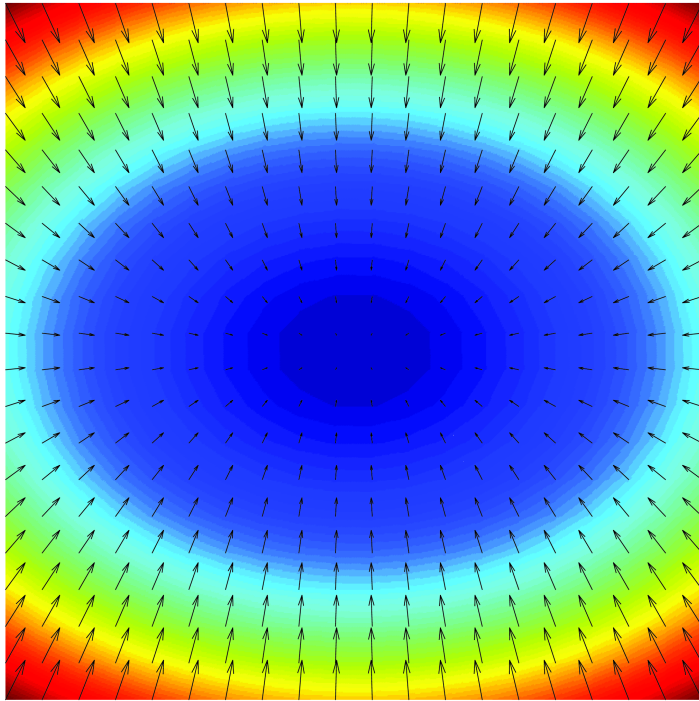
$$X = \ker A \oplus \operatorname{im} A^* \quad Y = \operatorname{im} A \oplus \ker A^*$$

$$J(x) = \frac{1}{2} \|Ax - Py\|_Y^2 + \frac{1}{2} \|(1 - P)y\|_Y^2$$

Gradient and Hessian:

$$DJ(x) = A^*(Ax - y) \quad D^2J(x) = A^*A$$

Singular Hessians



Backus-Gilbert theory

From $Ax = y$ we have for $y' \in Y$

$$\langle y, y' \rangle_Y = \langle x, A^* y' \rangle_X$$

If $x' \in \text{im}A^*$ we can compute $\langle x, x' \rangle_X$ from the data

For $x' \in X$ we can approximate $\langle x, x' \rangle_X$ by finding:

$$\tilde{y}' = \arg \min_{y' \in Y} \|A^* y' - x'\|_X^2$$

$$|\langle x, x' \rangle_X - \langle y, \tilde{y}' \rangle_Y| \leq \|A^* \tilde{y}' - x'\|_X \|x\|_X$$

Back to the toy problem

Linear objective functional:

$$J(u) = \int_0^T \int_{\partial\Omega_1} wu \, dS \, dt$$

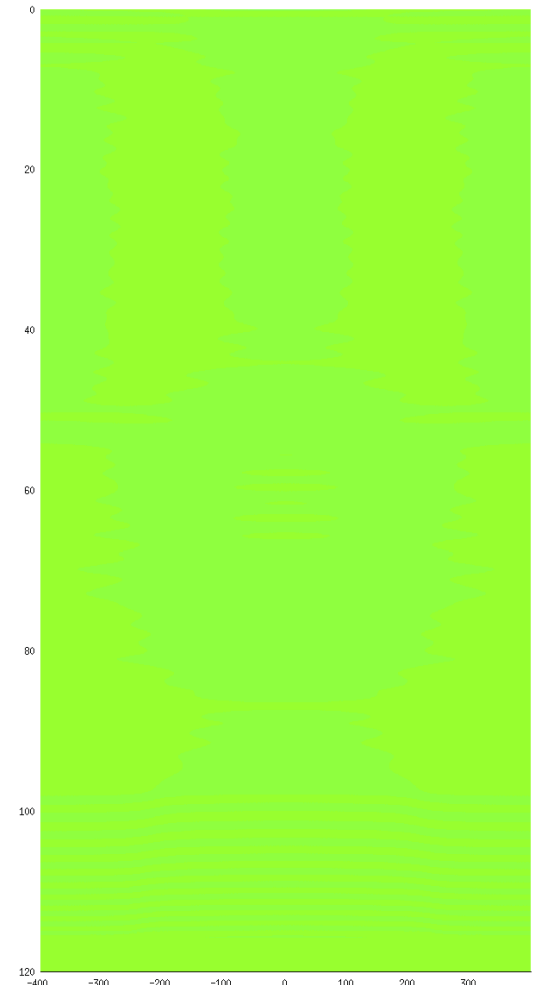
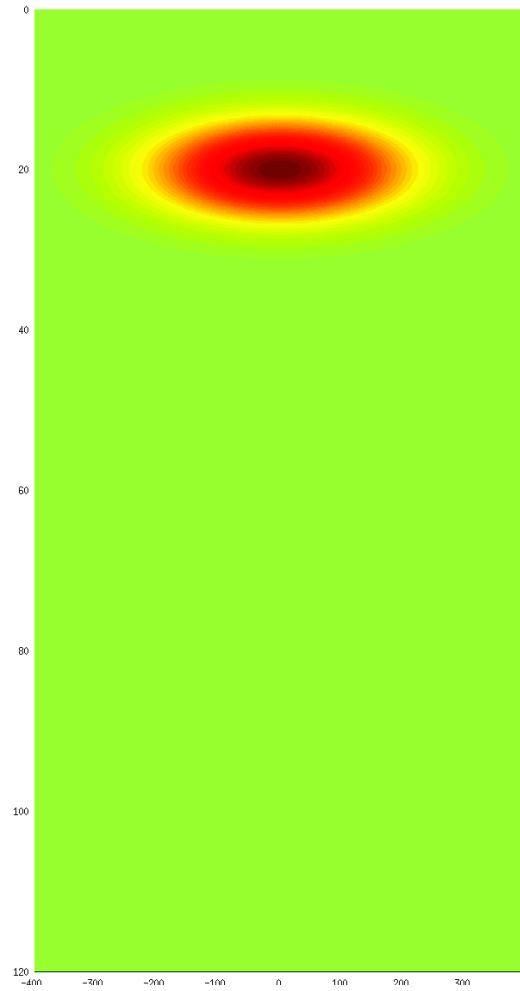
Derivative of reduced objective functional:

$$D_s \hat{J}(s) \{ \delta s \} = \int_0^T \int_{\partial\Omega_2} K_s \delta s \, dS \, dt$$

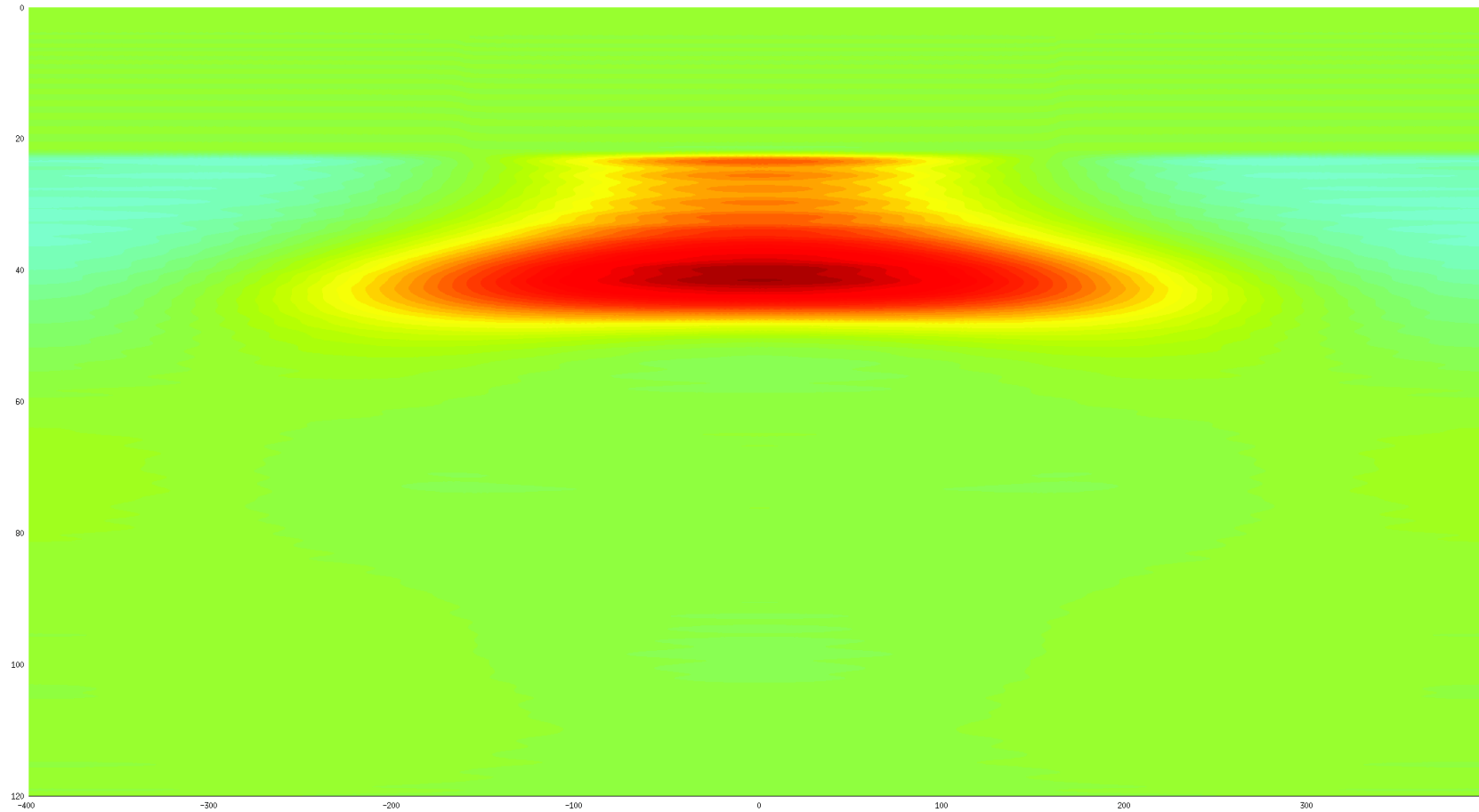
Secondary objective functional

$$J'(K_s) = \frac{1}{2} \int_0^T \int_{\partial\Omega_2} (K_s - h)^2 \, dS \, dt$$

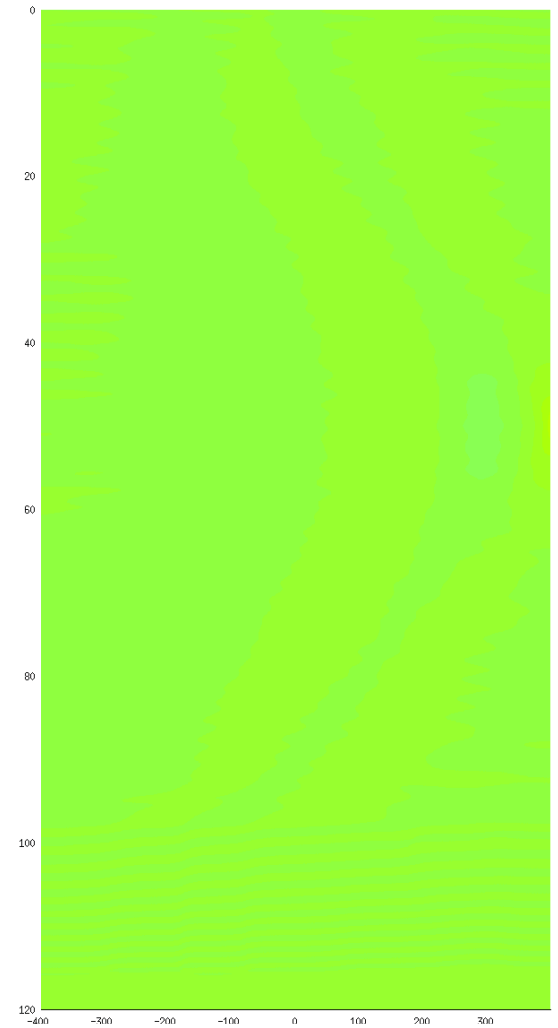
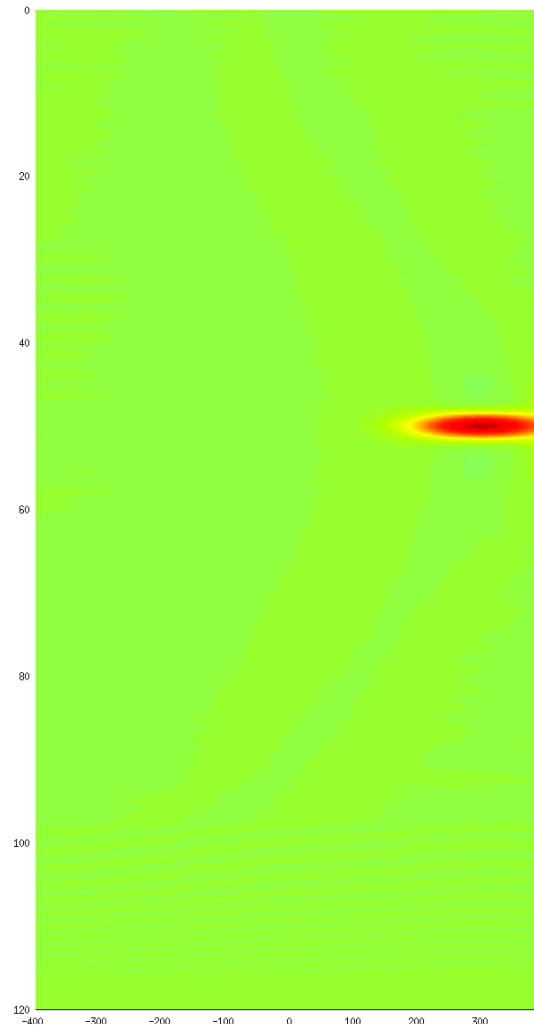
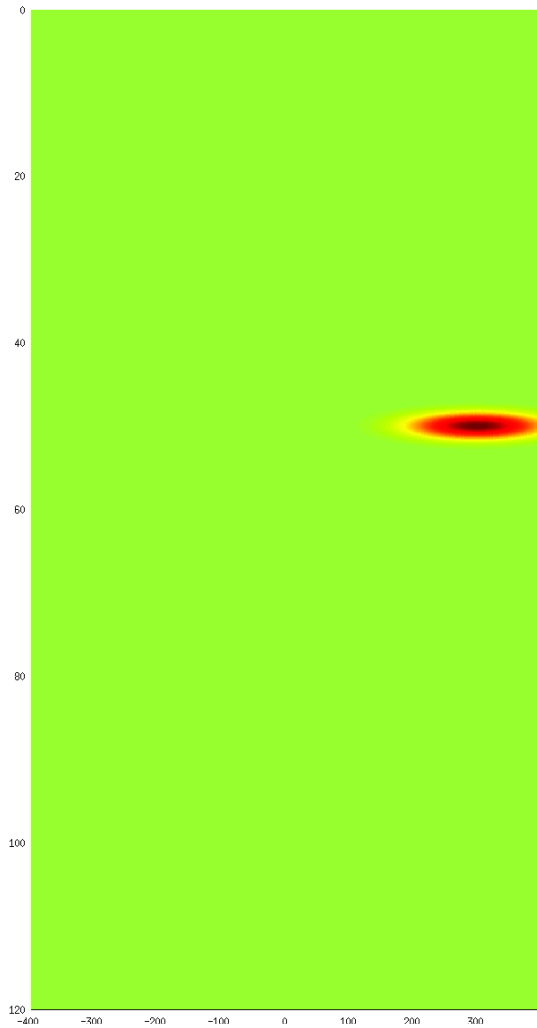
Kernel comparison



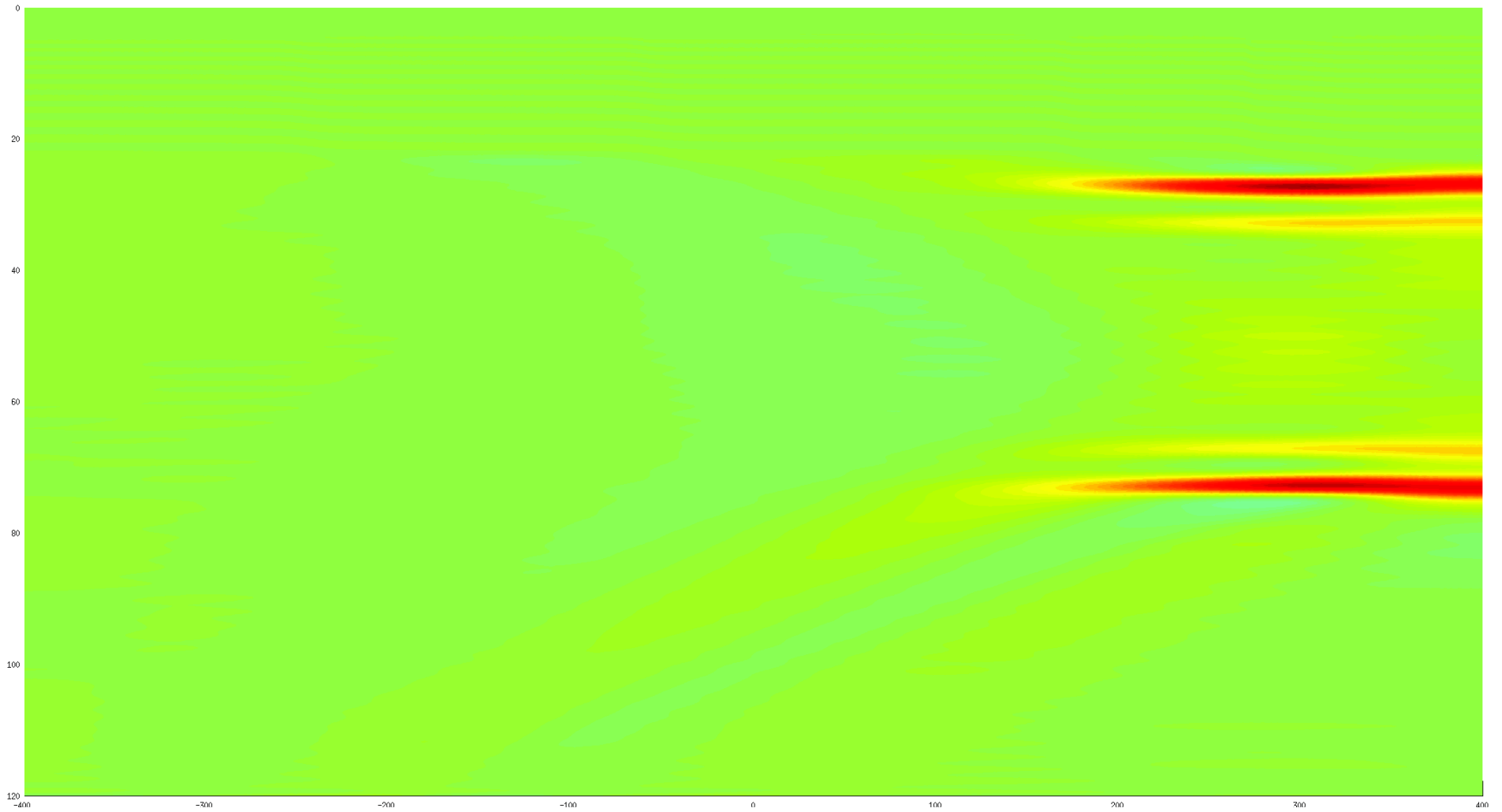
Optimal data functional



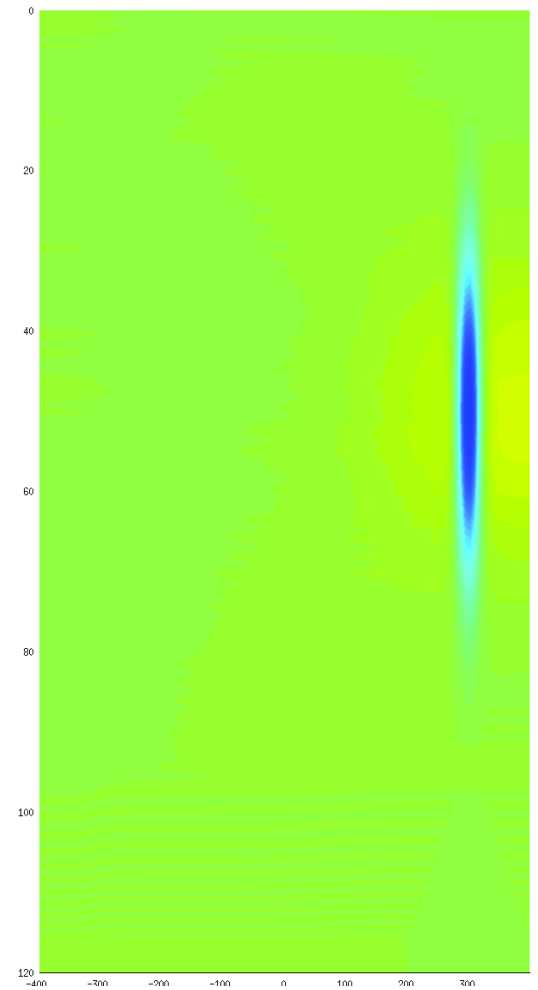
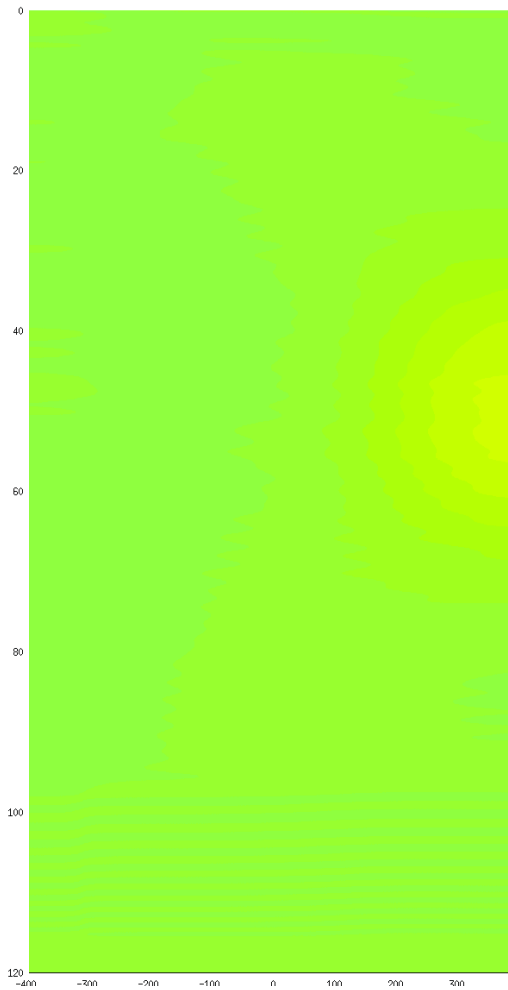
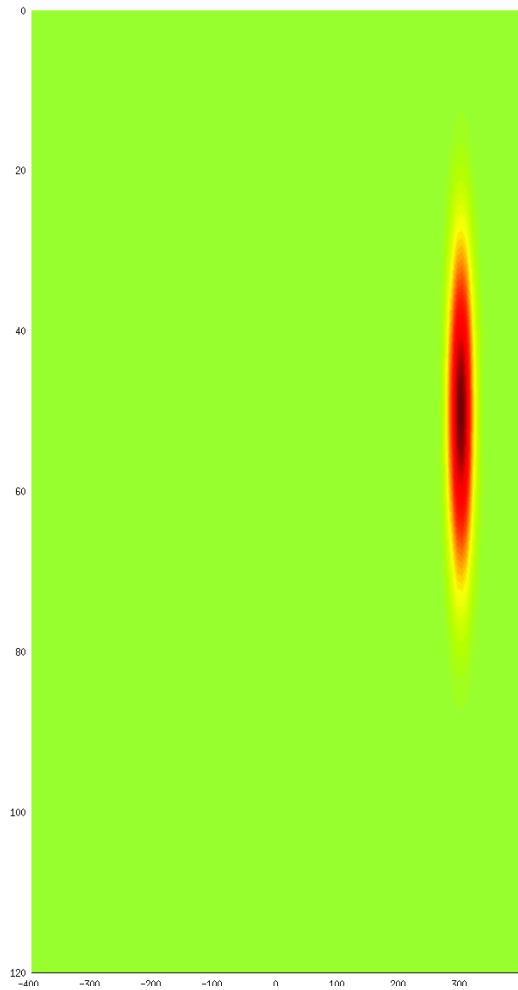
Kernel comparison



Optimal data functional



Kernel comparison



Summary

Convergence of gradient-based methods depends on starting model if problem is under-determined and not regularized

Backus-Gilbert theory provides a useful alternative to data-fitting methods

By using adjoint methods, Backus-Gilbert theory can be implemented iteratively in problems with large data-sets

Some of these ideas extend to non-linear problems ...